Decision Making and Inference Under Model Misspecification

Jose Blanchet.

Stanford University (Management Science and Engineering), and Institute for Computational and Mathematical Engineering).

Goal:

Goals: a) Introduce optimal transport methods popular applications and properties, then
b) use these results for robust performance analysis and finally c) also show how optimal transport applied to statistical estimation.

Agenda

• Day 1: Introduction to Optimal Transport (Primals and Duals)

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- Day 2: Distributionally robust performance analysis and optimization.

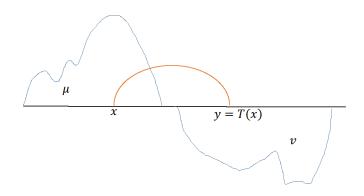
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- Day 1: Introduction to Optimal Transport (Primals and Duals)
- Day 2: Distributionally robust performance analysis and optimization.
- Day 3: Statistical properties of estimators.

Introduction to Optimal Transport

Monge-Kantorovich Problem & Duality (see e.g. C. Villani's 2008 textbook)

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- where $c(x, y) \ge 0$ is the cost of transporting x to y.
- $T(X) \sim v$ means T(X) follows distribution $v(\cdot)$.
- Problem is highly non-linear, not much progress for about 160 yrs!

• Let $\Pi(\mu, \nu)$ be the class of joint distributions π of random variables (X, Y) such that

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Linear programming (infinite dimensional):

$$\begin{split} D_{c}\left(\mu,v\right) & : & = \min_{\pi(dx,dy)\geq 0} \int_{\mathcal{X}\times\mathcal{Y}} c\left(x,y\right)\pi\left(dx,dy\right) \\ & \int_{\mathcal{Y}} \pi\left(dx,dy\right) = \mu\left(dx\right), \int_{\mathcal{X}} \pi\left(dx,dy\right) = v\left(dy\right). \end{split}$$

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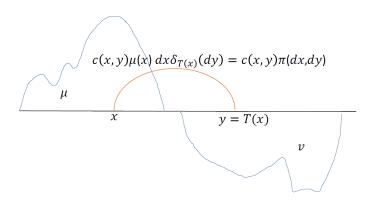
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• If c(x, y) = d(x, y) (d-metric) then $D_c(\mu, \nu)$ is a metric <- We'll check this later (this is Wasserstein distance).

Illustration of Optimal Transport Costs

Monge's solution would take the form

$$\pi^{*}\left(\mathrm{d}x,\mathrm{d}y\right)=\delta_{\left\{ T\left(x
ight)
ight\} }\left(\mathrm{d}y
ight)\mu\left(\mathrm{d}x
ight).$$



Warm up exercise to practice primal interpretation...

Warm up exercise: Check that $D_c(\cdot)$ is a metric if c(x,y) = d(x,y)where $d(\cdot)$ is a metric. i) $D_d(\mu, \nu) = D_d(\nu, \mu)$

ii) $D_d(\mu, \nu) \geq 0$ and $D_d(\mu, \nu) = 0$ if and only if $\mu = \nu$. iii) $D_d(\mu, w) \leq D_d(\mu, v) + D_d(v, w)$.

• Keep in mind primal:

$$D_{c}(\mu, v) := \min_{\pi(dx, dy) \geq 0} \int_{\mathcal{X} \times \mathcal{Y}} d(x, y) \pi(dx, dy)$$
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- Primal always has a solution (if c is lower semicontinuous) -> easy to see if $\mathcal Y$ and $\mathcal X$ are compact.
- If $D_d(\mu, \nu) = 0$, then $E_{\pi^*}(d(X, Y)) = 0$, then $X = Y \pi^*$ a.s. so $\mu(A) = \pi(X \in A) = \pi(Y \in A) = \nu(A)$.

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• Pick X, Y, Z so that $X \sim \mu$, $Y \sim v$ and $Z \sim w$. Sample $Y \sim v$ and then X|Y = y from the optimal coupling solving $D_d(\mu, v)$. Also, sample Z|Y = y using optimal coupling for computing $D_d(v, w)$.

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- On the other hand, $d(X, Z) \leq d(X, Y) + d(Y, Z)$ because $d(\cdot)$ is a metric.

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- Previous construction gives a coupling for X and Z, which is not necessarily optimal for computing $D_d(\mu, w)$.
- On the other hand, $d(X, Z) \leq d(X, Y) + d(Y, Z)$ because $d(\cdot)$ is a metric.
- Thus $D_d(\mu, w) \le E(d(X, Z)) \le D_d(\mu, v) + D_d(v, w)$.

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Towards the Dual Problem

It is always natural to study the dual of a linear programming problem...

Primal:

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• Dual:

$$\sup_{\alpha,\beta} \int_{\mathcal{X}} \alpha(x) \mu(dx) + \int_{\mathcal{Y}} \beta(y) v(dy)$$
$$\alpha(x) + \beta(y) \le c(x,y) \quad \forall (x,y) \in \mathcal{X} \times \mathcal{Y}.$$

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- Now comes Victoria, who has a business...
- Vicky promises to transport on behalf of Martin and Henry the whole amount.

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Kantorovich Relaxation: Primal Interpretation

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$$\int \alpha(x) \mu(dx) + \int \beta(y) v(dy).$$

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• Existence of dual optimizers: $c(x, y) \le a(x) + b(y)$ so $E_u a(X) < \infty$, $E_u b(Y) < \infty$.

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Proof Technique: Sketch of Strong Duality

ullet Suppose ${\mathcal X}$ and ${\mathcal Y}$ compact

$$\inf_{\pi \geq 0} \sup_{\alpha,\beta} \left\{ \int_{\mathcal{X} \times \mathcal{Y}} c(x,y) \, \pi(dx,dy) - \int_{\mathcal{X} \times \mathcal{Y}} \alpha(x) \, \pi(dx,dy) + \int_{\mathcal{X}} \alpha(x) \, \mu(dx) - \int_{\mathcal{X} \times \mathcal{Y}} \beta(y) \, \pi(dx,dy) + \int_{\mathcal{Y}} \beta(y) \, v(dy) \right\}$$

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- Swap sup and inf using Sion's min-max theorem by a compactness argument and conclude.
- Some amount of work to extend to general Polish spaces.

Application of Optimal Transport in Economics

Economic Interpretations & Some Closed Form Solutions (see e.g. A. Galichon's 2016 textbook & McCann 2013 notes).

• Worker with skill x & company with technology y yield $\Psi(x,y)$ surplus.

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Companies want to minimize total production cost

$$\int \alpha(x) \mu(x) dx + \int \beta(y) v(y) dy$$

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ullet Over assignments $\pi\left(\cdot\right)$ which satisfy market clearing

$$\int_{\mathcal{Y}} \pi(dx, dy) = \mu(dx), \ \int_{\mathcal{X}} \pi(dx, dy) = v(dy).$$

• Suppose that $\Psi(x, y) = xy$, $\mu(x) = I(x \in [0, 1])$, $\nu(y) = e^{-y}I(y > 0)$.

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$$F_{\mu_n}(x) = \frac{1}{n} \sum_{i=1}^n I(X_i^n \le x), \ F_{\nu_n}(y) = \frac{1}{n} \sum_{j=1}^n I(Y_j^n \le y)$$

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Consider

$$\begin{aligned} & \max_{\pi\left(x_{i}^{n},x_{j}^{n}\right) \geq 0} \sum_{i,j} \Psi\left(x_{i}^{n},y_{j}^{n}\right) \pi\left(x_{i}^{n},y_{j}^{n}\right) \\ & \sum_{j} \pi\left(x_{i}^{n},y_{j}^{n}\right) = \frac{1}{n} \, \forall x_{i}, \quad \sum_{i} \pi\left(x_{i}^{n},y_{j}^{n}\right) = \frac{1}{n} \, \forall y_{j}. \end{aligned}$$

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• Clearly, simply sort and match is the solution!

• Think of $Y_j^n = -\log\left(1 - U_j^n\right) = F_v^{-1}\left(U_j^n\right)$ for U_j^n s i.i.d. uniform(0,1).

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- Thus, the optimal coupling as $n \to \infty$ is X = U and $Y = -\log(1 U)$ (comonotonic coupling).

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- Thus, the optimal coupling as $n \to \infty$ is X = U and $Y = -\log(1 U)$ (comonotonic coupling).
- ullet In general, the optimal coupling is $X=F_{\mu}^{-1}\left(U
 ight)$ and $Y=F_{\nu}^{-1}\left(U
 ight)$.

• Comonotonic coupling is the solution if $\partial_{x,y}^2 \Psi(x,y) \ge 0$ -supermodularity:

$$\Psi\left(x\vee x',y\vee y'\right)+\Psi\left(x\wedge x',y\wedge y'\right)\geq\Psi\left(x,y\right)+\Psi\left(x',y'\right)$$

• Comonotonic coupling is the solution if $\partial_{x,y}^2 \Psi(x,y) \ge 0$ -supermodularity:

$$\Psi\left(x \lor x', y \lor y'\right) + \Psi\left(x \land x', y \land y'\right) \ge \Psi\left(x, y\right) + \Psi\left(x', y'\right)$$

• Or, for costs $c(x,y) = -\Psi(x,y)$, if $\partial_{x,y}^2 c(x,y) \le 0$ (submodularity).

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- Corollary: Suppose $c\left(x,y\right)=|x-y|$ then $X=F_{\mu}^{-1}\left(U\right)$ and $Y=F_{\nu}^{-1}\left(U\right)$ thus

$$D_{c}\left(F_{\mu}, F_{\nu}\right) = \int_{0}^{1} \left|F_{\mu}^{-1}\left(u\right) - F_{\nu}^{-1}\left(u\right)\right| du$$
$$= \int_{-\infty}^{\infty} \left|F_{\mu}\left(x\right) - F_{\nu}\left(x\right)\right| dx.$$

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$$\Psi\left(x \lor x', y \lor y'\right) + \Psi\left(x \land x', y \land y'\right) \ge \Psi\left(x, y\right) + \Psi\left(x', y'\right)$$

- Or, for costs $c(x,y) = -\Psi(x,y)$, if $\partial_{x,y}^2 c(x,y) \le 0$ (submodularity).
- Corollary: Suppose $c\left(x,y\right)=\left|x-y\right|$ then $X=F_{u}^{-1}\left(U\right)$ and $Y = F_{..}^{-1}(U)$ thus

$$D_{c}(F_{\mu}, F_{\nu}) = \int_{0}^{1} \left| F_{\mu}^{-1}(u) - F_{\nu}^{-1}(u) \right| du$$
$$= \int_{-\infty}^{\infty} \left| F_{\mu}(x) - F_{\nu}(x) \right| dx.$$

Similar identities are common for Wasserstein distances...

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• In equilibrium, by the envelope theorem

$$\dot{\beta}^{*}(y) = \frac{d}{dy} \sup_{x} \left[\Psi(x, y) - \alpha^{*}(x) \right] = \frac{\partial}{\partial y} \Psi(x_{y}, y) = x_{y}$$

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$$\beta^{*}\left(y\right) = y + \exp\left(-y\right) - 1 + \beta^{*}\left(0\right).$$

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• What if $\Psi(x,y) \to \Psi(x,y) + f(x)$? (i.e. productivity changes).

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23 / 115

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- What if $\Psi(x,y) \to \Psi(x,y) + f(x)$? (i.e. productivity changes).
- Answer: salaries increase if $f(\cdot)$ is increasing.

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Additional properties of Optimal Transport Solutions: Kantorovich-Rubinstein Duality and Wasserstein GAN.

• Consider the case c(x, y) = d(x, y).

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- Recall dual

$$\begin{aligned} & \max E_{\mu}\alpha\left(X\right) - E_{\nu}\beta\left(Y\right) \\ & s.t. \ \alpha\left(x\right) - \beta\left(y\right) \leq d\left(x,y\right) \ \forall \ x,y \in \mathcal{S} \ . \end{aligned}$$

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• Note that given β , we should pick

$$\alpha(x) = \beta^{d}(x) := \inf_{y} \{ \beta(y) + d(x, y) \},$$

similarly once $\alpha\left(\cdot\right)$ is chosen, we could improve by picking

$$\beta^{dd}(y) = \sup_{x} \{\beta^{d}(x) - d(x, y)\}.$$

Transforms are Lipschitz

• Moreover, observe that $\beta^{d}\left(\cdot\right)$ is 1-Lipschitz

$$\begin{split} \beta^{d}\left(x\right) &= \inf_{y}\{\beta\left(y\right) + d\left(x,y\right)\} < \text{- recall def} \\ \beta^{d}\left(x\right) - \beta^{d}\left(x'\right) &= \beta\left(y_{x}\right) + d\left(x,y_{x}\right) \\ &-\beta\left(y_{x'}\right) - d\left(x,y_{x'}\right) \\ &\leq d\left(x,y_{x'}\right) - d\left(x,y_{x'}\right) \leq d\left(x,x'\right). \end{split}$$

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• Same argument is true for $\beta^{dd}(y)$.

The Transform of a Lipschitz Function is the Function Itself

Moreover.

$$\beta^{d}(x) := \inf_{y} \left\{ \beta(y) + d(x, y) \right\} \le \beta(x)$$

and if β is 1-Lipschitz (meaning $|\beta(x) - \beta(y)| \le d(x, y)$) then

$$\beta^{d}(x) - \beta(x) = \inf_{y} \{d(x, y) + \beta(y) - \beta(x)\}$$

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ullet Consequently, if eta is 1-Lipschitz $eta=eta^d...$ So, the dual can be simplified.

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Back to Wasserstein Distances

• Original Dual:

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Simplified Dual (called Kantorovich duality result):

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 This is the basis for so-called Wasserstein GAN (Generative Adversarial Networks) – popular in artificial intelligence.

 Have you even thought about how to generate a "face" at random? (https://github.com/hindupuravinash/the-gan-zoo).



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What's the formulation

$$\min_{\theta < \text{NN parameter}} D_d \left(\textit{v}_{\theta}, \mu_\textit{n} \right) \text{,}$$

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- Use another Neural Network to parameterize α (i.e. a 1-Lip function).
- Apply automatic differentiation to compute gradients & run stochastic gradient descent.

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• So, in the end the dual is simplified to

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- But given x, equality holds if and only if $y \in \partial a(x) < -$ subdifferential (by convex analysis).
- Similarly, given y, if and only if $x \in \partial \alpha^*(y)$.
- But by Rademacher's theorem $\alpha\left(\cdot\right)$ is differentiable almost everywhere. So, given $X\sim\mu,\ Y=\nabla\alpha\left(X\right)$.

• Consequently, this establishes Brennier's Theorem: If $c(x, y) = ||x - y||_2^2 / 2$ then the optimal coupling

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 (by complementary slackness).

• Therefore $\nabla \bar{\alpha}\left(x\right) \in \partial \alpha\left(x\right)$ and by Rademacher $\nabla \bar{\alpha} = \nabla \alpha$ almost surely.

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• Example: Suppose that $X \sim N(0, I)$ and $Y \sim N(0, \Sigma)$ we want to transport X into Y optimally using the cost $c(x, y) = ||x - y||_2^2 / 2$.

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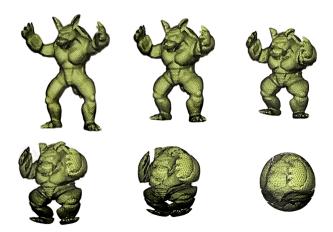
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- So, we must have that $A \cdot A = \Sigma$, the solution is that A is the polar factorization of Σ .
- From here it is easy to derive what the general optimal transport map is between two Gaussians (try this as an exercise).

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Illustration of Optimal Transport in Image Analysis

• Santambrogio (2010)'s illustration



The discussion is based on

B. & Murthy (2016)

https://arxiv.org/abs/1604.01446.

https://pubsonline.informs.org/doi/abs/10.1287/moor.2018.0936?journalCod

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- Model P_{true} might be unknown or too difficult to work with.
- So, we introduce a proxy P_0 which provides a good trade-off between tractability and model fidelity (e.g. Brownian motion for random walk approximations).

• For $f(\cdot)$ upper semicontinuous with $E_{P_0}|f(X)| < \infty$

$$\sup E_{P}\left(f\left(Y\right)\right)$$

$$D_{c}\left(P, P_{0}\right) \leq \delta ,$$

X takes values on a Polish space and $c\left(\cdot\right)$ is lower semi-continuous.

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Also an infinite dimensional linear program

$$\sup \int_{\mathcal{X} \times \mathcal{Y}} f(y) \pi(dx, dy)$$
s.t.
$$\int_{\mathcal{X} \times \mathcal{Y}} c(x, y) \pi(dx, dy) \leq \delta$$

$$\int_{\mathcal{Y}} \pi(dx, dy) = P_0(dx).$$

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Formal duality:

Dual =
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B. & Murthy (2016) - No duality gap:

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- We refer to this as RoPA Duality in this talk.
- Let us consider an important case first: $f(y) = I(y \in A) \& c(x, x) = 0$.

• So, if $f(y) = I(y \in A)$ and $c_A(X) = \inf\{y \in A : c(x,y)\}$, then $Dual = \inf_{\lambda > 0} \left[\lambda \delta + E_0(1 - \lambda c_A(X))^+\right] = P_0(c_A(X) \le 1/\lambda_*).$

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$$\textit{Dual} = \inf_{\lambda \geq 0} \left[\lambda \delta + \textit{E}_{0} \left(1 - \lambda \textit{c}_{\textit{A}} \left(X \right) \right)^{+} \right] = \textit{P}_{0} \left(\textit{c}_{\textit{A}} \left(X \right) \leq 1 / \lambda_{*} \right).$$

• If $c_{A}\left(X\right)$ is continuous under P_{0} & $E_{0}\left(c_{A}\left(X\right)\right)\geq\delta$, then

$$\delta = E_0 \left[c_A \left(X \right) I \left(c_A \left(X \right) \le 1/\lambda_* \right) \right].$$

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- B is a set which models bankruptcy.
- **Problem:** Model (P_{true}) may be complex, intractable or simply unknown...

• Our solution: Estimate u_T by solving

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where P_0 is a *suitable* model.

• P_0 = proxy for P_{true} .

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- $D_c(\cdot)$ is the distributional uncertainty region.

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- Optimal transport is a natural option!

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Application 1: Back to Classical Risk Problem

Suppose that

$$\begin{array}{lcl} c\left(x,y\right) & = & d_{J}\left(x\left(\cdot\right),y\left(\cdot\right)\right) = \mathsf{Skorokhod}\ J_{1}\ \mathsf{metric}. \\ & = & \inf_{\phi\left(\cdot\right)\ \mathsf{bijection}}\big\{\sup_{t\in[0,1]}\left|x\left(t\right)-y\left(\phi\left(t\right)\right)\right|, \sup_{t\in[0,1]}\left|\phi\left(t\right)-t\right|\big\}. \end{array}$$

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• If R(t) = b - Z(t), then ruin during time interval [0,1] is

$$B_{b}=\left\{ R\left(\cdot\right):0\geq\inf_{t\in\left[0,1\right]}R\left(t\right)\right\} =\left\{ Z\left(\cdot\right):b\leq\sup_{t\in\left[0,1\right]}Z\left(t\right)\right\} .$$

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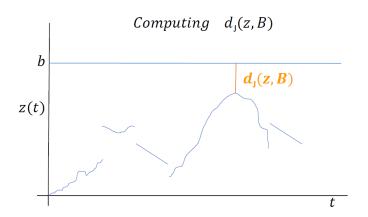
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• Let $P_0(\cdot)$ be the Wiener measure want to compute

$$\sup_{D_c(P_0,P)\leq\delta}P\left(Z\in B_b\right).$$

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Application 1: Computing Distance to Bankruptcy



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Application 1: Computing Uncertainty Size

• Note any coupling π so that $\pi_X = P_0$ and $\pi_Y = P$ satisfies

$$D_{c}(P_{0}, P) \leq E_{\pi}[c(X, Y)] \approx \delta.$$

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- ullet We discuss choosing δ non-parametrically momentarily.

Application 1: Illustration of Coupling

ullet Given arrivals and claim sizes let $Z\left(t
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Algorithm 1 To embed the process $(Z(t):t \ge 0)$ in Brownian motion $(B(t):t \ge 0)$ Given: Brownian motion B(t), moment m_1 and independent realizations of claim sizes X_1, X_2, \ldots

Initialize $\tau_0 := 0$ and $\Psi_0 := 0$. For $j \ge 1$, recursively define,

$$\tau_{j+1} := \inf\bigg\{s \geq \tau_j : \sup_{\tau_j \leq r \leq s} B_r - B_s = X_{j+1}\bigg\}, \text{ and } \Psi_j := \Psi_{j-1} + X_j.$$

Define the auxiliary processes

$$\tilde{S}(t) := \sum_{j>0} \sup_{\tau_j \leq s \leq t} B(s) \mathbf{1} \left(\tau_j \leq t < \tau_{j+1} \right) \text{ and } \tilde{N}(t) := \sum_{j \geq 0} \Psi_j \mathbf{1} (\tau_j \leq t < \tau_{j+1}).$$

Let $A(t) := \tilde{N}(t) + \tilde{S}(t)$, and identify the time change $\sigma(t) := \inf\{s : A(s) = m_1 t\}$. Next, take the time changed version $Z(t) := \tilde{S}(\sigma(t))$.

Replace Z(t) by -Z(t) and B(t) by -B(t).

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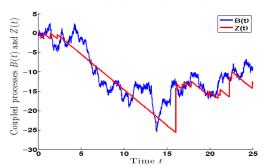
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• See also Fomivoch, Gonzalez-Cazares, Ivanovs (2021).

Application 1: Coupling in Action

FIGURE 4. A coupled path output by Algorithm 1



Application 1: Numerical Example

- Assume Poisson arrivals.
- Pareto claim sizes with index **2.2** $(P(V > t) = 1/(1+t)^{2.2})$.
- Cost $c(x, y) = d_J(x, y)^2 < -$ note power of 2.
- Used Algorithm 1 to calibrate (estimating means and variances from data).

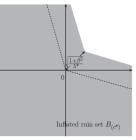
$$\begin{array}{cccc} b & \frac{P_0(\mathrm{Ruin})}{P_{true}(\mathrm{Ruin})} & \frac{P_{robust}^*(\mathrm{Ruin})}{P_{true}(\mathrm{Ruin})} \\ 100 & 1.07 \times 10^{-1} & 12.28 \\ 150 & 2.52 \times 10^{-4} & 10.65 \\ 200 & 5.35 \times 10^{-8} & 10.80 \\ 250 & 1.15 \times 10^{-12} & 10.98 \\ \end{array}$$

• See also Birghila, Aigner, Engelke (2021)

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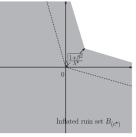
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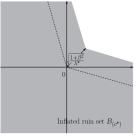


(b)Computation of worst-case ruin using the baseline measure

• Multidimensional risk processes (explicit evaluation of $c_B(x)$ for d_J metric).

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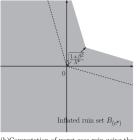


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- Key insight: Geometry of target set often remains largely the same!

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- Key insight: Geometry of target set often remains largely the same!

Background: (Very) Simplified version of Demand Side Platforms (DSPs)



Goal of DSP: Maximize revenue on behalf of advertisers

• Until recently, most exchanges operated using second price auctions.

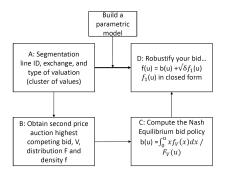
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- Now, first price auction exchanges have become popular.
- How to transfer information from second-price exchanges into first-price exchanges?

Transfer Information and Mitigation of Model Error

Summary of blue print $A \rightarrow B \rightarrow C \rightarrow D$



Notations

- $U_i = (\text{dlls/1000})$ value of the item in auction *i* if we win. We write $U_i = u_i$ when value is given.
- $b_i = (dlls/1000)$ is what we bid in the *i*-th auction (cost in 1st price auction).
- $V_i = (dlls/1000)$ is the highest competing bid in the *i*-th auction.
- f_{V_i} = the probability density function of V_i .
- F_{V_i} = the cumulative distribution function of V_i .

A Simplified Model:

$$\max_{\{b_1,...,b_n\}} \frac{1}{n} \sum_{i=1}^n (u_i - b_i) P(V_i \le b_i | U_i = u_i),$$

where n is the number of auctions in a given time period, for instance, a day.

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Also assume conditional independence.

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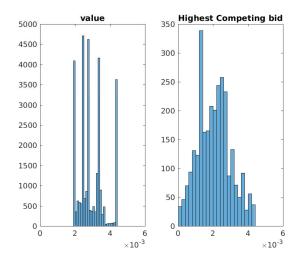
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- We go back to this in part II)...

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Inducing Homogeneity and Conditional Independence



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It turns out that

 $D(F,G) = \min\{E(|X-Y|) \text{ over all joint distributions}$ such that X has CDF F and Y has CDF G.

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$$\max_{D(F,F_V) \leq \delta} \bar{F}\left(b\right) = \max_{D(F,F_V) \leq \delta} P_F\left(V > b\right) = P_F\left(V > b - \lambda_b\right).$$

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• Let $\lambda = \lambda_b \ge 0$ be a Lagrange multiplier, the "worst case distribution" is

$$V^* = V \cdot I(V > b) + b \cdot I(b - \lambda < V \le b) + V \cdot I(V \le b - \lambda).$$

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• Intuitively: re-arrange V as cheaply as possible to produce V^* so that $V^* > b$ happens (λ computed to satisfy cost constraint).

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• Conclusion: We are trying to find the (Nash Equilibrium) policy $b^*(u) = f(u)$ so

$$\max_{b} \min_{D(F,F_{\bar{V}}) \leq \delta} (u-b) F_{\bar{V}} (f^{-1}(b))$$

$$= \max_{b} (u-b) F_{\bar{V}} (f^{-1}(b) - \lambda_{f^{-1}(b)}).$$

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$$\begin{split} & \max_{b} \min_{D(F,F_{\tilde{V}}) \leq \delta} \left(u - b \right) F_{\tilde{V}} \left(f^{-1} \left(b \right) \right) \\ & = & \max_{b} \left(u - b \right) F_{\tilde{V}} \left(f^{-1} \left(b \right) - \lambda_{f^{-1}(b)} \right). \end{split}$$

• Optimizing over $b(\cdot)$ we obtain

$$b\left(u\right) = \frac{\int_{0}^{u} x f_{\bar{V}}\left(x - \lambda_{x}\right) \left(1 - \dot{\lambda}\left(x\right)\right) dx}{F_{\bar{V}}\left(u - \lambda_{u}\right)},$$

with

$$\int_{u-\lambda_{u}}^{u}\left(u-v\right)f_{\bar{V}}\left(v\right)dv=\delta.$$

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Approximate Distributionally Robust Equilibrium Bidding Policies

• While the previous equations can be solved numerically, they may be a bit cumbersome to implement.

Approximate Distributionally Robust Equilibrium Bidding Policies

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Approximate Distributionally Robust Equilibrium Bidding **Policies**

- While the previous equations can be solved numerically, they may be a bit cumbersome to implement.
- So, we provide an asymptotic expansion as $\delta \to 0$.
- This leads to a bidding strategy of the form

$$b_{\delta}(u) = b_{0}(u) + \delta^{1/2}b_{1}(u) + O(\delta),$$

where

$$b_{0}\left(u\right)=E\left(\bar{V}|\bar{V}\leq u\right)=\int_{0}^{u}xf_{\bar{V}}\left(x\right)dx/F_{\bar{V}}\left(x\right)$$

and

$$b_{1}\left(u\right)=\frac{\sqrt{2}}{F_{\bar{V}}\left(u\right)}\left(\int_{0}^{u}\sqrt{f_{\bar{V}}\left(x\right)}dx-\frac{f_{\bar{V}}\left(u\right)}{F_{\bar{V}}\left(u\right)}\int_{0}^{u}F_{\bar{V}}\left(x\right)dx\right).$$

Example

• Example 3: Back to logistic model

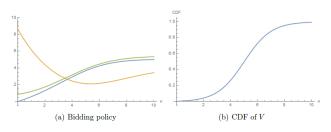
Example

- Example 3: Back to logistic model
- $P(\bar{V} \le x) = (1 + \exp(-xc)) / (1 + \exp(a xc))$ for $a \in R$, c > 0.

Example

- Example 3: Back to logistic model
- $P(\bar{V} \le x) = (1 + \exp(-xc)) / (1 + \exp(a xc))$ for $a \in R$, c > 0.
- a = 5, c = 1 and $\delta = .01$ (figures in \$/1000)

We show the bidding policy and CDF for $a = 5, c = 1, \delta = 0.01$ in the following plot.



Our Goal

So, now we want to add a player optimizing a decision and play the game:

$$\min_{\theta} \max_{D(P,P_n) \leq \delta} E\left(I\left(X,\theta\right)\right).$$

Based on: Robust Wasserstein Profile Inference (B., Murthy & Kang '16) https://arxiv.org/abs/1610.05627

https://www.cambridge.org/core/journals/journal-of-applied-probability /article/abs/robust-wasserstein-profile-inference-and-applications-to-machine-learning

Distributionally Robust Optimization in Machine Learning

• Consider estimating $\beta_* \in R^m$ in linear regression

$$Y_i = \beta X_i + e_i$$
,

where $\{(Y_i, X_i)\}_{i=1}^n$ are data points.

Distributionally Robust Optimization in Machine Learning

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 \bullet Optimal Least Squares approach consists in estimating β_* via

$$\min_{\beta} E_{P_n} \left[\left(Y - \beta^T X \right)^2 \right] = \min_{\beta} \frac{1}{n} \sum_{i=1}^n \left(Y_i - \beta^T X_i \right)^2$$

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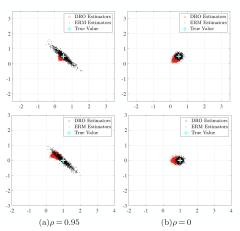
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 Apply the distributionally robust estimator based on optimal transport.

Applying Distributionally Robust Optimization in Linear Regression

Estimation of θ_* with DRO (\circ) and without DRO (\circ)



Connection to Sqrt-Lasso

Theorem (B., Kang, Murthy (2016)) Suppose that

$$c\left(\left(x,y\right),\left(x',y'\right)\right) = \begin{cases} \|x-x'\|_q^2 & \text{if } y=y'\\ \infty & \text{if } y\neq y' \end{cases}.$$

Then, if 1/p + 1/q = 1

$$\max_{P:D_c(P,P_n)\leq \delta} E_P^{1/2}\left(\left(Y-\beta^TX\right)^2\right) = E_{P_n}^{1/2}\left[\left(Y-\beta^TX\right)^2\right] + \sqrt{\delta} \left\|\beta\right\|_p.$$

Remark 1: This is sqrt-Lasso (Belloni et al. (2011)).

Classical classification model:

$$P(Y = 1|X) = \frac{\exp(\beta^T X)}{1 + \exp(\beta^T X)} = \frac{1}{\exp(-\beta^T X) + 1}$$
 $P(Y = -1|X) = \frac{1}{1 + \exp(\beta^T X)}$

Classical classification model:

$$egin{array}{lcl} P\left(Y=1|X
ight) &=& rac{\exp\left(eta^TX
ight)}{1+\exp\left(eta^TX
ight)} = rac{1}{\exp\left(-eta^TX
ight)+1} \ P\left(Y=-1|X
ight) &=& rac{1}{1+\exp\left(eta^TX
ight)} \end{array}$$

• The likelihood of (y, x) is:

$$-\log\left(1+\exp\left(-y\beta^Tx\right)\right)$$

• Therefore, given $\{(y_i, x_i)\}_{i=1}^n$ maximum likelihood is equivalent to

$$\max_{\beta} - \sum_{i=1}^{n} \log \left(1 + \exp \left(-y_{i} \beta^{T} x_{i} \right) \right).$$

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Also equivalent to

$$\min_{\beta} E_{P_n} \left[\log \left(1 + \exp \left(-Y \beta^T X \right) \right) \right]$$

$$= \min_{\beta} \frac{1}{n} \sum_{i=1}^{n} \log \left(1 + \exp \left(-y_i \beta^T x_i \right) \right).$$

Regularized Logistic Regression

Theorem (B., Kang, Murthy (2016)) Suppose that

$$c\left(\left(x,y\right),\left(x',y'\right)\right) = \left\{ \begin{array}{cc} \left\|x-x'\right\|_{q} & \text{if} \quad y=y'\\ \infty & \text{if} \quad y \neq y' \end{array} \right..$$

Then,

$$\begin{aligned} \sup_{P: \ \mathcal{D}_c(P,P_n) \leq \delta} E_P \left[\log(1 + e^{-Y\beta^T X}) \right] \\ = E_{P_n} \left[\log(1 + e^{-Y\beta^T X}) \right] + \delta \left\| \beta \right\|_p. \end{aligned}$$

Remark 1: First studied via an approximation in Esfahani and Kuhn (2015).

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Connection to Support Vector Machines

Theorem (B., Kang, Murthy (2016)) Suppose that

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Then,

$$\sup_{P: \ \mathcal{D}_{c}(P,P_{n}) \leq \delta} E_{P}\left[\left(1 - Y\beta^{T}X\right)^{+}\right]$$

$$= E_{P_{n}}\left[\left(1 - Y\beta^{T}X\right)^{+}\right] + \delta \left\|\beta\right\|_{p}.$$

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• Distributionally Robust Optimization using Optimal Transport recovers many other estimators...

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- See the excellent tutorials by Kuhn et al (2019) and Rahimian & Mehrotra (2019).
- Other areas in which optimal transport arises in machine learning

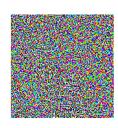
Deep Neural Networks: Adversarial Attacks

 $+.007 \times$

 Szegedy, Zaremba, Sutskever, Bruna, Erhan, Goodfellow, and Fergus (2014).



x
"panda"
57.7% confidence



 $sign(\nabla_{\boldsymbol{x}}J(\boldsymbol{\theta},\boldsymbol{x},y))$ "nematode" 8.2% confidence



 $x + \epsilon sign(\nabla_x J(\theta, x, y))$ "gibbon"
99.3 % confidence

Deep Neural Networks: Adversarial Attacks

• Sharif, Bhagavatula, Bauer, and Reiter (2016)













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Deep Neural Networks: Adversarial Attacks

Picture from the BBC

Chinese man caught by facial recognition at pop concert



Chinese police have used facial recognition technology to locate and arrest a man who was among a crowd of 60,000 concert goers.

• Let us work out a simple example...

- Let us work out a simple example...
- Recall RoPA Duality: Pick $c((x, y), (x', y')) = ||(x, y) (x', y')||_q^2$

$$\max_{P:D_{c}(P,P_{n})\leq\delta} E_{P}\left(\left((X,Y)\cdot(\beta,1)\right)^{2}\right)$$

$$= \min_{\lambda\geq0} \left\{\lambda\delta + E_{P_{n}} \sup_{(x',y')} \left[\left((x',y')\cdot(\beta,1)\right)^{2} - \lambda \left\|(X,Y) - (x',y')\right\|_{C}^{2}\right\}\right\}$$

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• Let's focus on the inside E_{P_n} ...

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• Let
$$\Delta = (X, Y) - (x', y')$$

$$\sup_{\substack{(x', y') \\ \Delta}} \left[\left((x', y') \cdot (\beta, 1) \right)^2 - \lambda \left\| (X, Y) - (x', y') \right\|_q^2 \right]$$

$$= \sup_{\Delta} \left[\left((X, Y) \cdot (\beta, 1) - \Delta \cdot (\beta, 1) \right)^2 - \lambda \left\| \Delta \right\|_q^2 \right]$$

$$= \sup_{\|\Delta\|_q} \left[\left(\left| (X, Y) \cdot (\beta, 1) \right| + \|\Delta\|_q \left\| (\beta, 1) \right\|_p \right)^2 - \lambda \left\| \Delta \right\|_q^2 \right]$$

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$$= \sup_{\Delta} \left[\left((X, Y) \cdot (\beta, 1) - \Delta \cdot (\beta, 1) \right)^2 - \lambda \left\| \Delta \right\|_q^2 \right]$$

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• Last equality uses $z \to z^2$ is symmetric around origin and $|a \cdot b| \le ||a||_p ||b||_q$.

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How Regularization and Dual Norms Arise?

• Let
$$\Delta = (X, Y) - (x', y')$$

$$\sup_{\substack{(x', y') \\ \Delta}} \left[\left((x', y') \cdot (\beta, 1) \right)^2 - \lambda \left\| (X, Y) - (x', y') \right\|_q^2 \right]$$

$$= \sup_{\Delta} \left[\left((X, Y) \cdot (\beta, 1) - \Delta \cdot (\beta, 1) \right)^2 - \lambda \left\| \Delta \right\|_q^2 \right]$$

$$= \sup_{\|\Delta\|_q} \left[\left(\left| (X, Y) \cdot (\beta, 1) \right| + \left\| \Delta \right\|_q \left\| (\beta, 1) \right\|_p \right)^2 - \lambda \left\| \Delta \right\|_q^2 \right]$$

- Last equality uses $z \to z^2$ is symmetric around origin and $|a \cdot b| \le ||a||_p ||b||_q$.
- Note problem is now one-dimensional (easily computable).

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A Fully Worked Out Example: Support Vector Machines

• Use RoPA: with

$$c\left(\left(x,y\right),\left(x',y'\right)\right) = \left\|x - x'\right\|_{q} I\left(y = y'\right) + \infty I\left(y \neq y'\right)$$

$$\sup_{P \in \mathcal{D}_{c}(P,P_{n}) \leq \delta} E_{P}\left[\left(1 - Y\beta^{T}X\right)^{+}\right]$$

$$= \min_{\lambda \geq 0} \left[\lambda \delta + E_{P_{n}} \left\{\max_{x} \left(\left(1 - Y\beta^{T}x\right)^{+} - \lambda \left\|x - X\right\|_{q}\right)\right\}\right]$$

$$= \min_{\lambda \geq 0} \left[\lambda \delta + E_{P_{n}} \left\{\max_{x} \left(\left(1 - Y\beta^{T}X - Y\beta^{T}\Delta\right)^{+} - \lambda \left\|\Delta\right\|_{q}\right)\right\}\right]$$

$$= \min_{\lambda \geq 0} \left[\lambda \delta + E_{P_{n}} \left\{\max_{\Delta} \left(\left(1 - Y\beta^{T}X + \left\|\beta\right\|_{p} \left\|\Delta\right\|_{q}\right)^{+} - \lambda \left\|\Delta\right\|_{q}\right)\right\}$$

$$= \min_{\lambda \geq \left\|\beta\right\|_{p}} \left[\lambda \delta + E_{P_{n}} \left\{\max_{\left\|\Delta\right\|_{q}} \left(\left(1 - Y\beta^{T}X + \left\|\beta\right\|_{p} \left\|\Delta\right\|_{q}\right)^{+} - \lambda \left\|\Delta\right\|_{q}\right)\right\}$$

$$= \min_{\lambda \geq \left\|\beta\right\|_{p}} \left[\lambda \delta + E_{P_{n}} \left(1 - Y\beta^{T}X\right)^{+}\right] = \lambda \left\|\beta\right\|_{p} + E_{P_{n}} \left(1 - Y\beta^{T}X\right)$$

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Explaining the Adversarial Attacks of Neural Networks

So, in general

$$c\left(\left(x,y\right),\left(x',y'\right)\right) = \left\|x - x'\right\|_{q} I\left(y = y'\right) + \infty I\left(y \neq y'\right)$$

$$\sup_{P: \ \mathcal{D}_{c}(P,P_{n}) \leq \delta} E_{P}[I\left(\theta,Y,X\right)]$$

$$= \min_{\lambda \geq 0} \left[\lambda \delta + E_{P_{n}} \left\{ \max_{x} \left(I\left(\theta,Y,x\right) - \lambda \left\|x - X\right\|_{q}\right)\right\} \right]$$

$$= \min_{\lambda \geq 0} \left[\lambda \delta + E_{P_{n}} \left\{ \max_{\Delta} \left(I\left(\theta,Y,X + \Delta\right) - \lambda \left\|\Delta\right\|_{q}\right)\right\} \right]$$

$$= \min_{\lambda \geq 0} \left[\lambda \delta + E_{P_{n}} \left\{ \max_{\Delta} \left(I\left(\theta,Y,X + \Delta/\lambda\right) - \left\|\Delta\right\|_{q}\right)\right\} \right].$$

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Explaining the Adversarial Attacks of Neural Networks

 So, in general $c((x, y), (x', y')) = ||x - x'||_a I(y = y') + \infty I(y \neq y')$ $\sup_{P: \mathcal{D}_{c}(P,P_{n}) \leq \delta} E_{P}[I(\theta, Y, X)]$ $= \min_{\lambda > 0} \left[\lambda \delta + E_{P_n} \left\{ \max_{x} \left(I(\theta, Y, x) - \lambda \|x - X\|_q \right) \right\} \right]$

$$= \min_{\lambda \geq 0} \left[\lambda \delta + E_{P_n} \left\{ \max_{\Delta} \left(I(\theta, Y, X + \Delta) - \lambda \|\Delta\|_q \right) \right\} \right]$$

$$= \min_{\lambda \geq 0} \left[\lambda \delta + E_{P_n} \left\{ \max_{\Delta} \left(I(\theta, Y, X + \Delta/\lambda) - \|\Delta\|_q \right) \right\} \right].$$

• If $\delta \approx 0$, then λ is large, so inner maximization

$$\begin{aligned} & \max_{\Delta} \left(I\left(\theta, Y, X + \Delta/\lambda\right) - \left\|\Delta\right\|_{q} \right) \\ & \approx & I\left(\theta, Y, X\right) + \left\|I_{x}\left(\theta, Y, X\right)\right\|_{p} \left\|\Delta\right\|_{q} / \lambda - \left\|\Delta\right\|_{q} \end{aligned}$$

Summary

ullet The worst case perturbation is given by Δ such that

$$I_{X}(\theta, Y, X) \cdot \Delta / \lambda = \|I_{X}(\theta, Y, X)\|_{p} \|\Delta\|_{q} / \lambda,$$

if $q = \infty$, then $\Delta = c \cdot sign(I_X(\theta, Y, X))$.

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if $q = \infty$, then $\Delta = c \cdot sign(I_X(\theta, Y, X))$.

• So, $\delta \approx 0$ means perturbing by

$$\epsilon \cdot sign(I_{x}(\theta, Y, X))$$

for $\epsilon > 0$.

• This explains the nature of the panda example given earlier.

Naturally, it makes sense then to train networks using

$$\begin{split} & \min_{\theta} \max_{D(P,P_n) \leq \delta} E_P\left(I\left(\theta,Y,X\right)\right) \\ &= & \min_{\theta} \{\lambda\delta + E_{P_n} \max_{x} [I\left(\theta,Y,x\right) - \lambda \left\|x - X\right\|_q]. \end{split}$$

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- This will automatically protect against attacks.
- This is an active area of research currently.
- But there may be many possible attacks.

• https://arxiv.org/abs/1705.07152: Data-driven chose of $c(\cdot)$.

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- Suppose that $\|x x'\|_A^2 = (x x') A(x x)$ with A positive definite (Mahalanobis distance).

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• Intuition: Think of A diagonal, encoding inverse variability of X_i s...

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- Intuition: Think of A diagonal, encoding inverse variability of X_i s...
- High variability —> cheap transportation —> high impact in risk estimation.

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ullet Intuition: Think of Λ diagonal, encoding inverse variability of X_i s...

- https://arxiv.org/abs/1705.07152: Data-driven chose of $c(\cdot)$.
- Suppose that $\|x x'\|_{\Lambda}^2 = (x x') \Lambda(x x)$ with Λ positive definite (Mahalanobis distance).
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- Intuition: Think of Λ diagonal, encoding inverse variability of X_i s...
- High variability —> cheap transportation —> high impact in risk estimation.

Connections to Statistical Analysis

https://arxiv.org/abs/1610.05627 Robust Wasserstein Profile Inference B., Murthy & Kang '16

https://arxiv.org/abs/1906.01614

Confidence Regions in Wasserstein Distributionally Robust Estimation
B., Murthy & Si '19
Optimal size of uncertainty + Asymptotic Normality

• How to choose uncertainty size in a data-driven way?

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$$= \min_{\beta} E_{P_{n}}^{1/2} \left[\left(Y - \beta^{T} X \right)^{2} \right] + \sqrt{\delta} \left\| \beta \right\|_{p}.$$

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- ullet Use left hand side to define a statistical principle to choose δ .
- ullet Important: Optimizing δ is equivalent to optimizing regularization.

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$$D(P_{true}, P_n) = \sup_{\alpha \in Lip(1)} E_{P_{true}} \alpha(X) - E_{P_n} \alpha(X)$$
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• Unfortunately, it turns out that typically $D\left(P_{true}, P_n\right) = O\left(n^{-1/d}\right)$ (Dudley '68) for d > 2.

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- For k-fold cross validation to be consistent you need $k/n \to 1$ and $n-k \to \infty$ (Shao '93).
- So, for model selection you need k increasing.

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- Given $P \in \mathcal{U}_{\delta}(n)$, define $\bar{\beta}(P) = \arg\min E_P \left| \left(Y \beta^T X \right)^2 \right|$.
- It is natural to say that

$$\Lambda_{\delta}\left(\mathbf{n}\right)=\left\{ ar{eta}\left(P
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are plausible estimates of β_* .

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- In simple words: Find the smallest δ so that β_* is plausible with confidence level $1-\alpha$.

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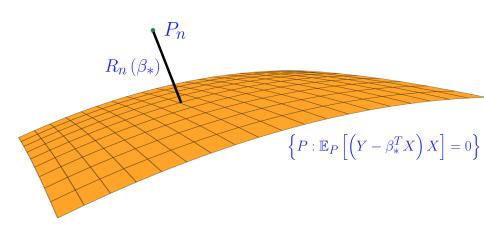
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• So δ is $1 - \alpha$ quantile of $R_n(\beta_*)!$

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Computing Optimal Regularization Parameter

Theorem (B., Murthy, Kang (2016)) Suppose that $\{(Y_i, X_i)\}_{i=1}^n$ is an i.i.d. sample with finite variance, with

$$c\left(\left(x,y\right),\left(x',y'\right)\right) = \begin{cases} \|x-x'\|_q^2 & \text{if } y=y' \\ \infty & \text{if } y\neq y' \end{cases}$$

then

$$nR_n(\beta_*) \Rightarrow L_1$$
,

where L_1 is explicitly (to be computed in one moment)

$$L_1 \stackrel{D}{\leq} L_2 := \frac{E[e^2]}{Var(e)} \|N(0, Cov(X))\|_q^2.$$

Remark: We recover same order of regularization (but L_1 gives the optimal constant!)

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• Compute η_{α} the quantile of L_1 (we'll see that L_1 is explicit) – say for $\alpha=.95$.

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- The distribution of L_1 also depends on Cov(X) but you again can use any consistent plug-in estimator.
- ullet So, using all of these estimators compute η_{lpha} and let $\delta=\eta_{lpha}/n$.

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- There is a broader connection to hypothesis testing (applications to fairness are explored in https://arxiv.org/abs/2012.04800)
- Next, we'll see what is L_1 in the more general hypothesis testing setting.

More Generally Projections to Linear Manifolds

Let

$$\mathcal{M} = \{P : E_P h_i(X) = 0 \text{ for } i = 1, ..., m\}$$

(i.e. distribution that are similar to P_* based on characteristics h_i)

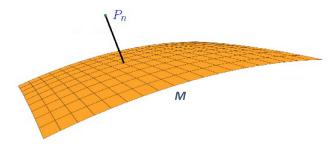
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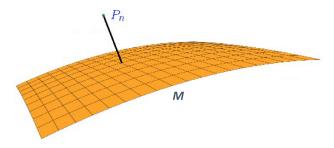
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 \bullet P_n is the empirical measure on some data set.

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Duality Results

Theorem (B., Kang, Murthy '19)

Suppose that $c\left(x,y\right)\geq0$ is lower semicontinuous and define $H\left(x\right)=\left(h_{1}\left(x\right),...,h_{m}\left(x\right)\right)^{T}\in\mathbb{R}^{m}$ and suppose that $E_{P_{*}}\left(H\left(X\right)\right)$ is in the interior of $\{H\left(x\right):x\in\mathbb{R}^{d}\}$, then

$$R_{n} = \max_{\lambda \in R^{m}} \left\{ -E_{P_{n}} \left(\sup_{y} \left\{ \lambda^{T} H(y) - c(X, y) \right\} \right) \right\}$$

Some Comments on Proof: Finite Support Essential

Primal:

$$\min \int \int c(x, y) \pi(dx, dy)$$

$$\int \int h_i(y) \pi(dx, dy) = 0 \text{ for all } i = 1, ..., m.$$

$$\int \pi(dx, dy) = P_n(dx); \quad \pi(dx, dy) \ge 0.$$

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• Dual:

$$\sup_{\lambda \in \mathbb{R}^{m}} E_{P_{n}} \alpha \left(X \right)$$

$$\lambda^{T} H \left(y \right) + \alpha \left(x \right) \leq c \left(x, y \right) \text{ for } x \in \left\{ X_{i} \right\}_{i=1}^{n}, y \in \mathbb{R}^{d}.$$

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 Proof technique reduces to problem of moments (finitely many constraints in primal crucial).

Statistics: Limiting Distribution

Theorem (B., Kang, Murthy '19)

Suppose $c\left(x,y\right)=\left\|x-y\right\|^2$ for $r\geq 1$ (and $\left\|z\right\|_*=\sup_{\left\|x\right\|\leq 1}x^Tz$ is the dual norm of $\left\|\cdot\right\|$). Assume that duality holds and that $Cov_{P_*}\left(H\left(X\right)\right)=G$ exists. Then (under regularity assumptions to be discussed) if $P_*\in\mathcal{M}$ (recall $P_*=P_\infty$ the data generating distribution)

$$nR_n \Rightarrow \psi^*(Z) = \sup_{\theta} [\theta \cdot Z - \psi(\theta)],$$

where $Z \sim N(0, G)$ and

$$\psi\left(\theta\right) = E_{P_*} \left[\left\| \theta^T DH\left(X\right) \right\|_*^2 \right].$$

Remark: So, the solution is $\psi^*(Z)$ is a quadratic form of the Gaussian. Let's study the structure of the projection.

Blanchet (Stanford) 100 / 115

Intuition and Insights from the Proof

• By defining applying duality

$$R_{n} = \max_{\lambda} \left\{ -E_{P_{n}} \max_{\Delta} \left[\lambda^{T} H \left(X + \Delta \right) - \left\| \Delta \right\|^{2} \right] \right\}.$$

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- $R_n = O\left(n^{-1}\right)$ because $R_n^{1/2} =$ distance to match constraints $= O\left(n^{-1/2}\right)$.

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- Guessing scalings: $\Delta = O\left(n^{-1/2}\right)$ (since only $O\left(n^{-1/2}\right)$ transport will match constraints by the CLT).
- $R_n = O(n^{-1})$ because $R_n^{1/2}$ =distance to match constraints = $O(n^{-1/2})$.
- $\lambda =$ sensitivity with respect to change in constraints = $O\left(n^{-1}/n^{-1/2}\right) = O\left(n^{-1/2}\right)$.

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• Substitute $\Delta \leftarrow \Delta/n^{1/2}$:

$$R_{n} = \max_{\lambda} \left\{ -E_{P_{n}} \max_{\Delta} \left[\lambda^{T} H \left(X + \Delta / n^{1/2} \right) - \left\| \Delta / n^{1/2} \right\|^{2} \right] \right\}$$

$$= \max_{\lambda} \left\{ -\lambda^{T} E_{P_{n}} H \left(X \right) - E_{P_{n}} \max_{\Delta} \left[\lambda^{T} \left(H \left(X + \Delta / n^{1/2} \right) - H \left(X \right) \right) - \left\| \Delta / n^{1/2} \right\|^{2} \right] \right\}.$$

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• Substitute $\lambda \leftarrow \lambda n^{-1/2}$ and use $H\left(X + \Delta/n^{1/2}\right) - H\left(X\right) \approx DH\left(X\right) \Delta/n^{1/2}$: $\max_{\lambda} \left\{-n^{-1/2} \lambda^T E_{P_n}\left(H\left(X\right)\right) - E_{P_n} \max_{\Delta} \left[n^{-1} \lambda^T DH\left(X\right) \Delta - n^{-1} \left\|\Delta\right\|^2\right]\right\}$ $= n^{-1/2} \max_{\lambda} \left\{-n^{1/2} \lambda^T E_{P_n}\left(H\left(X\right)\right)\right\}$

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• Already can see all the elements in the result (at least formally) since $n^{1/2}\lambda^T E_{P_n}H(X) \Rightarrow \lambda^T Z$ (by the CLT).

 $-E_{P_n} \max_{\Delta} \left| \lambda^T DH(X) \Delta - \|\Delta\|^2 \right|$.

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Conclude by noting

$$E_{P_n} \max_{\Delta} \left[\lambda^T DH(X) \Delta - \|\Delta\|^2 \right]$$

$$= E_{P_n} \max_{\Delta} \left[\left\| \lambda^T DH(X) \right\|_* \|\Delta\| - \|\Delta\|^2 \right],$$

with $\Delta_{opt}\left(X\right)$ dual ("parallel") to $\lambda^T D \bar{H}\left(X\right)$ and with $\left\|\Delta_{opt}\left(X\right)\right\| = 2^{-1} \left\|\lambda^T D \bar{H}\left(X\right)\right\|_*$.

Conclude by noting

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• The map $X \to X + \Delta_{opt} \left(X \right) / n^{1/2}$ characterizes the optimal transport projection plan.

Conclude by noting

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- This provides the elements and the intuition.
- Rigorous analysis requires compactifying over λ .

Infinite Dimensional Case

What about the infinite dimensional case?

Statistics: Limiting Distribution

Theorem (Si, B., Ghosh, Squillante '20)

Suppose $c(x,y) = \|x - y\|_2^2$ and $C = \{f(\theta^T x) : \theta \in \{\theta_1, ..., \theta_m\}, f \in \mathcal{F}\}$. If domain is compact, under regularity conditions on \mathcal{F}

$$nR_n \Rightarrow L = \sup_{f \in \mathcal{L}(\mathcal{C})} [-2Z(f) - E_{P_*}(\|Df(X)\|^2)],$$

where Z(f) is a Gaussian random field such that $cov_{P_*}(Z(f), Z(g)) = cov_{P_*}(f(X), g(X))$.

Remark: Regularity condition, it is required that P_* has a density and that \mathcal{F} satisfies

$$\sup_{f \in \mathcal{L}(\mathcal{F})} \frac{\sup_{x \in \Omega} \left| f''\left(\theta_i^T x\right) \right|^2}{\int_{\Omega} \left(f'\left(\theta_i^T z\right) \right)^2 dz} < \infty.$$

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Comments

 Proof follows same elements as finite dimensional case (the compactification step is more involved).

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- Proof follows same elements as finite dimensional case (the compactification step is more involved).
- Natural connection to a Poincaré inequality of the form

$$Var_{P_*}\left(f\left(X\right)\right) \leq cE_{P_*}\left(\left\|Df\left(X\right)\right\|^2\right)$$

arises naturally in the limit.

Asymptotic Normality

Once we know how to choose the size of the uncertainty optimally we can obtain asymptotically optimal estimators

Statistics of Distributionally Robust Optimization

Theorem (B., Murthy, Si (2019) https://arxiv.org/pdf/1906.01614.pdf)

Assume that $\{X_i: 1 \leq i \leq n\}$ is an i.i.d. sample from P_* . Suppose $I(\cdot)$ is twice differentiable, $I(x,\cdot)$ convex, $C = E\left(D^2_{\beta}I(X,\beta_*)\right) \succ 0$ (where $\beta_* = \arg\min E_P\left(I(X,\beta)\right)$), then, with $\delta_n^* = \eta/n$

$$\begin{split} & n^{1/2} \left(\beta_n^{DRO} \left(0 \right) - \beta_* \right) & \Rightarrow & C^{-1} Z_0 \\ & n^{1/2} \left(\beta_n^{DRO} \left(\delta_n^* \right) - \beta_n^{ERM} \right) & \Rightarrow & \nabla v \left(\beta \right), \end{split}$$

Remark: Recall $Z_0 \sim N\left(0, Cov\left(D_{\beta}I\left(X, \beta_*\right)\right)\right)$ and $v\left(\beta\right) = \eta^{1/2} E_{P_n}^{1/2} \left\|D_xI\left(X, \beta\right)\right\|_q^2$

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• Recall the duality result with $\delta_n = \eta/n$

$$\begin{aligned} & \max_{D(P,P_n) \leq \delta_n} E_P\left(I\left(X,\beta\right)\right) \\ &= & \max_{\lambda} \{\frac{\lambda \eta}{n} + E_{P_n} \max_{\Delta} \{I\left(X + \Delta,\beta\right) - \lambda \left\|\Delta\right\|_p^2\}. \end{aligned}$$

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- From this form, it is easy to guess the result...
- Worst case adversary: $\Delta_{opt}(X_i)$ is parallel to $D_xI(X,\beta)$ & $\|\Delta_{opt}(X_i)\|_p = \|D_XI(X,\beta)\|_q/(2\lambda)$

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- $\Lambda_{\delta_n^*}(n)$ is the natural DRO confidence region & has desired coverage.

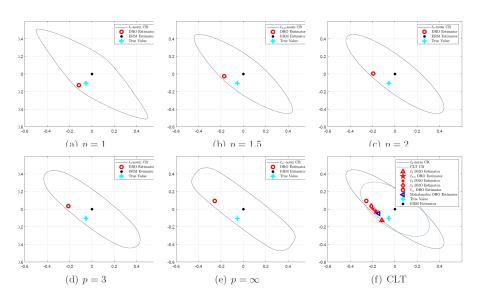
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Geometry of Confidence Region?



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Containment of the DRO Solution

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The fact that

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 It follows from the following duality result in B., Murthy and Si (2019) https://arxiv.org/pdf/1906.01614.pdf

$$\inf_{\beta} \sup_{D(P,P_n) \leq \delta} E_P I(X,\beta) = \sup_{D(P,P_n) \leq \delta} \inf_{\beta} E_P I(X,\beta).$$

Standard CLT May Not Contain the DRO Solution

TABLE 1. Coverage Fromability

β_0	ρ	ℓ_2 DRO confidence region		CLT confidence region	
		Coverage for β_n^{DRO}	Coverage for β_*	Coverage for β_n^{DRO}	Coverage for β_*
$\begin{bmatrix} 0.5 \\ 0.5 \end{bmatrix}$	0.95 0 -0.95	100.0% 100.0% 100.0%	94.5% 94.0% 94.8%	99.4% 97.1% 75.8%	94.6% 93.5% 94.4%
$\begin{bmatrix} 1.0 \\ 0.0 \end{bmatrix}$	0.95 0 -0.95	100.0% 100.0% 100.0%	$94.6\% \\ 94.6\% \\ 95.3\%$	93.7% 100% 91.2%	95.4% 94.1% 94.9%

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- Structure of the Nash equilibrium.
- Connections to interesting projection problem $R_n = D(P_n, \mathcal{M})$:

$$nD(P_n, \mathcal{M}) \Rightarrow L.$$