

Decision Making and Inference Under Model Misspecification

Jose Blanchet.

Stanford University (Management Science and Engineering), and Institute for Computational and Mathematical Engineering).

Goals: a) Introduce optimal transport methods popular applications and properties, then b) use these results for robust performance analysis and finally c) also show how optimal transport applied to statistical estimation.

- Day 1: Introduction to Optimal Transport (Primals and Duals)

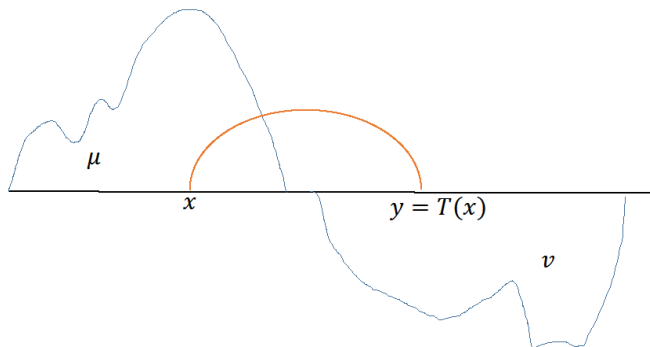
- Day 1: Introduction to Optimal Transport (Primals and Duals)
- Day 2: Distributionally robust performance analysis and optimization.

- Day 1: Introduction to Optimal Transport (Primals and Duals)
- Day 2: Distributionally robust performance analysis and optimization.
- Day 3: Statistical properties of estimators.

Monge-Kantorovich Problem & Duality
(see e.g. C. Villani's 2008 textbook)

Monge Problem

- What's the cheapest way to transport a pile of sand to cover a sinkhole?



Monge Problem

- What's the cheapest way to transport a pile of sand to cover a sinkhole?

$$\min_{T(\cdot): T(X) \sim \nu} E_{\mu} \{c(X, T(X))\},$$

Monge Problem

- What's the cheapest way to transport a pile of sand to cover a sinkhole?

$$\min_{T(\cdot): T(X) \sim \nu} E_{\mu} \{c(X, T(X))\},$$

- where $c(x, y) \geq 0$ is the cost of transporting x to y .

Monge Problem

- What's the cheapest way to transport a pile of sand to cover a sinkhole?

$$\min_{T(\cdot): T(X) \sim \nu} E_{\mu} \{c(X, T(X))\},$$

- where $c(x, y) \geq 0$ is the cost of transporting x to y .
- $T(X) \sim \nu$ means $T(X)$ follows distribution $\nu(\cdot)$.

Monge Problem

- What's the cheapest way to transport a pile of sand to cover a sinkhole?

$$\min_{T(\cdot): T(X) \sim \nu} E_{\mu} \{c(X, T(X))\},$$

- where $c(x, y) \geq 0$ is the cost of transporting x to y .
- $T(X) \sim \nu$ means $T(X)$ follows distribution $\nu(\cdot)$.
- Problem is highly non-linear, not much progress for about 160 yrs!

Kantorovich Relaxation: Primal Problem

- Let $\Pi(\mu, \nu)$ be the class of joint distributions π of random variables (X, Y) such that

$$\pi_X = \text{marginal of } X = \mu, \quad \pi_Y = \text{marginal of } Y = \nu.$$

Kantorovich Relaxation: Primal Problem

- Let $\Pi(\mu, \nu)$ be the class of joint distributions π of random variables (X, Y) such that

$$\pi_X = \text{marginal of } X = \mu, \quad \pi_Y = \text{marginal of } Y = \nu.$$

- Solve

$$\min\{E_\pi[c(X, Y)] : \pi \in \Pi(\mu, \nu)\}$$

Kantorovich Relaxation: Primal Problem

- Let $\Pi(\mu, \nu)$ be the class of joint distributions π of random variables (X, Y) such that

$$\pi_X = \text{marginal of } X = \mu, \quad \pi_Y = \text{marginal of } Y = \nu.$$

- Solve

$$\min\{E_\pi[c(X, Y)] : \pi \in \Pi(\mu, \nu)\}$$

- Linear programming (infinite dimensional):

$$D_c(\mu, \nu) : = \min_{\pi(dx, dy) \geq 0} \int_{\mathcal{X} \times \mathcal{Y}} c(x, y) \pi(dx, dy)$$
$$\int_{\mathcal{Y}} \pi(dx, dy) = \mu(dx), \quad \int_{\mathcal{X}} \pi(dx, dy) = \nu(dy).$$

Kantorovich Relaxation: Primal Problem

- Let $\Pi(\mu, \nu)$ be the class of joint distributions π of random variables (X, Y) such that

$$\pi_X = \text{marginal of } X = \mu, \quad \pi_Y = \text{marginal of } Y = \nu.$$

- Solve

$$\min\{E_\pi[c(X, Y)] : \pi \in \Pi(\mu, \nu)\}$$

- Linear programming (infinite dimensional):

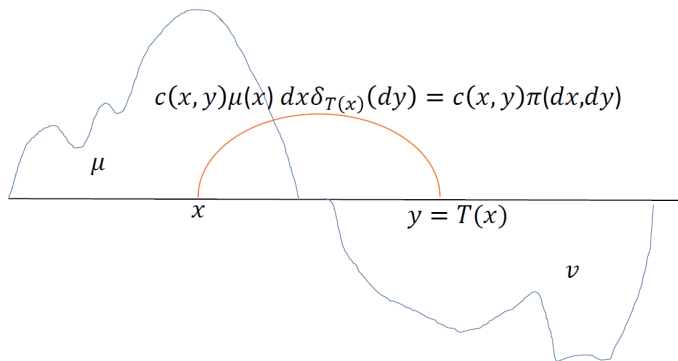
$$D_c(\mu, \nu) : = \min_{\pi(dx, dy) \geq 0} \int_{\mathcal{X} \times \mathcal{Y}} c(x, y) \pi(dx, dy)$$
$$\int_{\mathcal{Y}} \pi(dx, dy) = \mu(dx), \quad \int_{\mathcal{X}} \pi(dx, dy) = \nu(dy).$$

- If $c(x, y) = d(x, y)$ (d -metric) then $D_c(\mu, \nu)$ is a metric \leftarrow We'll check this later (this is Wasserstein distance).

Illustration of Optimal Transport Costs

- Monge's solution would take the form

$$\pi^* (dx, dy) = \delta_{\{T(x)\}} (dy) \mu (dx) .$$



Warm up exercise to practice primal interpretation...

Warm up exercise: Check that $D_c(\cdot)$ is a metric if $c(x, y) = d(x, y)$ where $d(\cdot)$ is a metric.

i) $D_d(\mu, \nu) = D_d(\nu, \mu)$

ii) $D_d(\mu, \nu) \geq 0$ and $D_d(\mu, \nu) = 0$ if and only if $\mu = \nu$.

iii) $D_d(\mu, w) \leq D_d(\mu, \nu) + D_d(\nu, w)$.

Kantorovich Relaxation: Primal Problem

- Keep in mind primal:

$$D_c(\mu, \nu) : = \min_{\pi(dx, dy) \geq 0} \int_{\mathcal{X} \times \mathcal{Y}} d(x, y) \pi(dx, dy)$$
$$\int_{\mathcal{Y}} \pi(dx, dy) = \mu(dx), \int_{\mathcal{X}} \pi(dx, dy) = \nu(dy).$$

Kantorovich Relaxation: Primal Problem

- Keep in mind primal:

$$D_c(\mu, \nu) : = \min_{\pi(dx, dy) \geq 0} \int_{\mathcal{X} \times \mathcal{Y}} d(x, y) \pi(dx, dy)$$
$$\int_{\mathcal{Y}} \pi(dx, dy) = \mu(dx), \int_{\mathcal{X}} \pi(dx, dy) = \nu(dy).$$

- Primal always has a solution (if c is lower semicontinuous) \rightarrow easy to see if \mathcal{Y} and \mathcal{X} are compact.

Kantorovich Relaxation: Primal Problem

- Keep in mind primal:

$$D_c(\mu, \nu) : = \min_{\pi(dx, dy) \geq 0} \int_{\mathcal{X} \times \mathcal{Y}} d(x, y) \pi(dx, dy)$$
$$\int_{\mathcal{Y}} \pi(dx, dy) = \mu(dx), \int_{\mathcal{X}} \pi(dx, dy) = \nu(dy).$$

- Primal always has a solution (if c is lower semicontinuous) \rightarrow easy to see if \mathcal{Y} and \mathcal{X} are compact.
- If $D_d(\mu, \nu) = 0$, then $E_{\pi^*}(d(X, Y)) = 0$, then $X = Y$ π^* a.s. so $\mu(A) = \pi(X \in A) = \pi(Y \in A) = \nu(A)$.

Kantorovich Relaxation: Primal Problem

- Now verify triangle inequality

$$D_d(\mu, w) \leq D_d(\mu, \nu) + D_d(\nu, w).$$

Kantorovich Relaxation: Primal Problem

- Now verify triangle inequality

$$D_d(\mu, w) \leq D_d(\mu, \nu) + D_d(\nu, w).$$

- Pick X, Y, Z so that $X \sim \mu$, $Y \sim \nu$ and $Z \sim w$. Sample $Y \sim \nu$ and then $X|Y = y$ from the optimal coupling solving $D_d(\mu, \nu)$. Also, sample $Z|Y = y$ using optimal coupling for computing $D_d(\nu, w)$.

Kantorovich Relaxation: Primal Problem

- Now verify triangle inequality

$$D_d(\mu, w) \leq D_d(\mu, \nu) + D_d(\nu, w).$$

- Pick X, Y, Z so that $X \sim \mu$, $Y \sim \nu$ and $Z \sim w$. Sample $Y \sim \nu$ and then $X|Y = y$ from the optimal coupling solving $D_d(\mu, \nu)$. Also, sample $Z|Y = y$ using optimal coupling for computing $D_d(\nu, w)$.
- Previous construction gives a coupling for X and Z , which is not necessarily optimal for computing $D_d(\mu, w)$.

Kantorovich Relaxation: Primal Problem

- Now verify triangle inequality

$$D_d(\mu, w) \leq D_d(\mu, \nu) + D_d(\nu, w).$$

- Pick X, Y, Z so that $X \sim \mu$, $Y \sim \nu$ and $Z \sim w$. Sample $Y \sim \nu$ and then $X|Y = y$ from the optimal coupling solving $D_d(\mu, \nu)$. Also, sample $Z|Y = y$ using optimal coupling for computing $D_d(\nu, w)$.
- Previous construction gives a coupling for X and Z , which is not necessarily optimal for computing $D_d(\mu, w)$.
- On the other hand, $d(X, Z) \leq d(X, Y) + d(Y, Z)$ because $d(\cdot)$ is a metric.

Kantorovich Relaxation: Primal Problem

- Now verify triangle inequality

$$D_d(\mu, w) \leq D_d(\mu, \nu) + D_d(\nu, w).$$

- Pick X, Y, Z so that $X \sim \mu$, $Y \sim \nu$ and $Z \sim w$. Sample $Y \sim \nu$ and then $X|Y = y$ from the optimal coupling solving $D_d(\mu, \nu)$. Also, sample $Z|Y = y$ using optimal coupling for computing $D_d(\nu, w)$.
- Previous construction gives a coupling for X and Z , which is not necessarily optimal for computing $D_d(\mu, w)$.
- On the other hand, $d(X, Z) \leq d(X, Y) + d(Y, Z)$ because $d(\cdot)$ is a metric.
- Thus $D_d(\mu, w) \leq E(d(X, Z)) \leq D_d(\mu, \nu) + D_d(\nu, w)$.

Towards the Dual Problem

It is always natural to study the dual of a linear programming problem...

- Primal:

$$\min_{\pi(dx, dy) \geq 0} \int_{\mathcal{X} \times \mathcal{Y}} d(x, y) \pi(dx, dy)$$
$$\int_{\mathcal{Y}} \pi(dx, dy) = \mu(dx), \int_{\mathcal{X}} \pi(dx, dy) = \nu(dy).$$

- Primal:

$$\min_{\pi(dx,dy) \geq 0} \int_{\mathcal{X} \times \mathcal{Y}} d(x,y) \pi(dx,dy)$$
$$\int_{\mathcal{Y}} \pi(dx,dy) = \mu(dx), \int_{\mathcal{X}} \pi(dx,dy) = \nu(dy).$$

- Dual:

$$\sup_{\alpha, \beta} \int_{\mathcal{X}} \alpha(x) \mu(dx) + \int_{\mathcal{Y}} \beta(y) \nu(dy)$$
$$\alpha(x) + \beta(y) \leq c(x,y) \quad \forall (x,y) \in \mathcal{X} \times \mathcal{Y}.$$

Kantorovich Relaxation: Dual Problem

- Primal:

$$\min_{\pi(dx, dy) \geq 0} \int_{\mathcal{X} \times \mathcal{Y}} d(x, y) \pi(dx, dy)$$
$$\int_{\mathcal{Y}} \pi(dx, dy) = \mu(dx), \quad \int_{\mathcal{X}} \pi(dx, dy) = \nu(dy).$$

- Dual:

$$\sup_{\alpha, \beta} \int_{\mathcal{X}} \alpha(x) \mu(dx) + \int_{\mathcal{Y}} \beta(y) \nu(dy)$$
$$\alpha(x) + \beta(y) \leq c(x, y) \quad \forall (x, y) \in \mathcal{X} \times \mathcal{Y}.$$

- Here α and β can be taken continuous

Kantorovich Relaxation: Primal Interpretation

- Martin wants to remove of a pile of sand, $\mu(\cdot)$.

Kantorovich Relaxation: Primal Interpretation

- Martin wants to remove of a pile of sand, $\mu(\cdot)$.
- Henry wants to cover a sinkhole, $\nu(\cdot)$.

Kantorovich Relaxation: Primal Interpretation

- Martin wants to remove a pile of sand, $\mu(\cdot)$.
- Henry wants to cover a sinkhole, $\nu(\cdot)$.
- Cost for Martin and Henry to transport the sand to cover the sinkhole is

$$D_c(\mu, \nu) = \int_{\mathcal{X} \times \mathcal{Y}} c(x, y) \pi^*(dx, dy).$$

Kantorovich Relaxation: Primal Interpretation

- Martin wants to remove a pile of sand, $\mu(\cdot)$.
- Henry wants to cover a sinkhole, $\nu(\cdot)$.
- Cost for Martin and Henry to transport the sand to cover the sinkhole is

$$D_c(\mu, \nu) = \int_{\mathcal{X} \times \mathcal{Y}} c(x, y) \pi^*(dx, dy).$$

- Now comes Victoria, who has a business...

Kantorovich Relaxation: Primal Interpretation

- Martin wants to remove a pile of sand, $\mu(\cdot)$.
- Henry wants to cover a sinkhole, $\nu(\cdot)$.
- Cost for Martin and Henry to transport the sand to cover the sinkhole is

$$D_c(\mu, \nu) = \int_{\mathcal{X} \times \mathcal{Y}} c(x, y) \pi^*(dx, dy).$$

- Now comes Victoria, who has a business...
- Vicky promises to transport on behalf of Martin and Henry the whole amount.

Kantorovich Relaxation: Primal Interpretation

- Vicky charges John $\alpha(x)$ per-unit of mass at x (similarly to Peter, $\beta(y)$).

Kantorovich Relaxation: Primal Interpretation

- Vicky charges John $\alpha(x)$ per-unit of mass at x (similarly to Peter, $\beta(y)$).
- For Peter and John to agree we must have

$$\alpha(x) + \beta(y) \leq c(x, y).$$

Kantorovich Relaxation: Primal Interpretation

- Vicky charges John $\alpha(x)$ per-unit of mass at x (similarly to Peter, $\beta(y)$).
- For Peter and John to agree we must have

$$\alpha(x) + \beta(y) \leq c(x, y).$$

- Vicky wishes to maximize her profit

$$\int \alpha(x) \mu(dx) + \int \beta(y) \nu(dy).$$

Kantorovich Relaxation: Primal Interpretation

- Vicky charges John $\alpha(x)$ per-unit of mass at x (similarly to Peter, $\beta(y)$).
- For Peter and John to agree we must have

$$\alpha(x) + \beta(y) \leq c(x, y).$$

- Vicky wishes to maximize her profit

$$\int \alpha(x) \mu(dx) + \int \beta(y) \nu(dy).$$

- Kantorovich duality says primal and dual optimal values coincide and

$$\alpha^*(x) + \beta^*(y) = c(x, y) - \pi^* \text{ a.s. } \leftarrow \text{complementary slackness}$$

Kantorovich Relaxation: Primal Interpretation

- Vicky charges John $\alpha(x)$ per-unit of mass at x (similarly to Peter, $\beta(y)$).
- For Peter and John to agree we must have

$$\alpha(x) + \beta(y) \leq c(x, y).$$

- Vicky wishes to maximize her profit

$$\int \alpha(x) \mu(dx) + \int \beta(y) \nu(dy).$$

- Kantorovich duality says primal and dual optimal values coincide and

$$\alpha^*(x) + \beta^*(y) = c(x, y) - \pi^* \text{ a.s. } \leftarrow \text{complementary slackness}$$

- Existence of dual optimizers: $c(x, y) \leq a(x) + b(y)$ so $E_\mu a(X) < \infty$, $E_\nu b(Y) < \infty$.

Proof Technique: Sketch of Strong Duality

- Suppose \mathcal{X} and \mathcal{Y} compact

$$\inf_{\pi \geq 0} \sup_{\alpha, \beta} \left\{ \int_{\mathcal{X} \times \mathcal{Y}} c(x, y) \pi(dx, dy) \right. \\ \left. - \int_{\mathcal{X} \times \mathcal{Y}} \alpha(x) \pi(dx, dy) + \int_{\mathcal{X}} \alpha(x) \mu(dx) \right. \\ \left. - \int_{\mathcal{X} \times \mathcal{Y}} \beta(y) \pi(dx, dy) + \int_{\mathcal{Y}} \beta(y) \nu(dy) \right\}$$

Proof Technique: Sketch of Strong Duality

- Suppose \mathcal{X} and \mathcal{Y} compact

$$\inf_{\pi \geq 0} \sup_{\alpha, \beta} \left\{ \int_{\mathcal{X} \times \mathcal{Y}} c(x, y) \pi(dx, dy) \right. \\ \left. - \int_{\mathcal{X} \times \mathcal{Y}} \alpha(x) \pi(dx, dy) + \int_{\mathcal{X}} \alpha(x) \mu(dx) \right. \\ \left. - \int_{\mathcal{X} \times \mathcal{Y}} \beta(y) \pi(dx, dy) + \int_{\mathcal{Y}} \beta(y) \nu(dy) \right\}$$

- Swap sup and inf using **Sion's min-max theorem** by a compactness argument and conclude.

Proof Technique: Sketch of Strong Duality

- Suppose \mathcal{X} and \mathcal{Y} compact

$$\inf_{\pi \geq 0} \sup_{\alpha, \beta} \left\{ \int_{\mathcal{X} \times \mathcal{Y}} c(x, y) \pi(dx, dy) \right. \\ \left. - \int_{\mathcal{X} \times \mathcal{Y}} \alpha(x) \pi(dx, dy) + \int_{\mathcal{X}} \alpha(x) \mu(dx) \right. \\ \left. - \int_{\mathcal{X} \times \mathcal{Y}} \beta(y) \pi(dx, dy) + \int_{\mathcal{Y}} \beta(y) \nu(dy) \right\}$$

- Swap sup and inf using **Sion's min-max theorem** by a compactness argument and conclude.
- *Some amount of work to extend to general Polish spaces.*

Economic Interpretations & Some Closed Form Solutions
(see e.g. A. Galichon's 2016 textbook & McCann 2013 notes).

Applications in Labor Markets

- Worker with skill x & company with technology y yield $\Psi(x, y)$ surplus.

Applications in Labor Markets

- Worker with skill x & company with technology y yield $\Psi(x, y)$ surplus.
- The population of workers is given by $\mu(x)$.

Applications in Labor Markets

- Worker with skill x & company with technology y yield $\Psi(x, y)$ surplus.
- The population of workers is given by $\mu(x)$.
- The population of companies is given by $v(y)$.

Applications in Labor Markets

- Worker with skill x & company with technology y yield $\Psi(x, y)$ surplus.
- The population of workers is given by $\mu(x)$.
- The population of companies is given by $\nu(y)$.
- The salary of worker x is $\alpha(x)$ & cost of technology y is $\beta(y)$

$$\alpha(x) + \beta(y) \geq \Psi(x, y).$$

Applications in Labor Markets

- Worker with skill x & company with technology y yield $\Psi(x, y)$ surplus.
- The population of workers is given by $\mu(x)$.
- The population of companies is given by $\nu(y)$.
- The salary of worker x is $\alpha(x)$ & cost of technology y is $\beta(y)$

$$\alpha(x) + \beta(y) \geq \Psi(x, y).$$

- Companies want to *minimize* total production cost

$$\int \alpha(x) \mu(x) dx + \int \beta(y) \nu(y) dy$$

Applications in Labor Markets

- Letting a central planner organize the Labor market.

Applications in Labor Markets

- Letting a central planner organize the Labor market.
- The planner wishes to maximize total surplus

$$\int \Psi(x, y) \pi(dx, dy)$$

Applications in Labor Markets

- Letting a central planner organize the Labor market.
- The planner wishes to maximize total surplus

$$\int \Psi(x, y) \pi(dx, dy)$$

- Over assignments $\pi(\cdot)$ which satisfy market clearing

$$\int_{\mathcal{Y}} \pi(dx, dy) = \mu(dx), \quad \int_{\mathcal{X}} \pi(dx, dy) = \nu(dy).$$

Solving for Optimal Transport Coupling

- **Suppose that** $\Psi(x, y) = xy$, $\mu(x) = 1(x \in [0, 1])$,
 $\nu(y) = e^{-y}1(y > 0)$.

Solving for Optimal Transport Coupling

- **Suppose that** $\Psi(x, y) = xy$, $\mu(x) = I(x \in [0, 1])$,
 $\nu(y) = e^{-y}I(y > 0)$.
- Solve primal by sampling: Let $\{X_i^n\}_{i=1}^n$ and $\{Y_i^n\}_{i=1}^n$ both i.i.d. from μ and ν , respectively.

$$F_{\mu_n}(x) = \frac{1}{n} \sum_{i=1}^n I(X_i^n \leq x), \quad F_{\nu_n}(y) = \frac{1}{n} \sum_{j=1}^n I(Y_j^n \leq y)$$

Solving for Optimal Transport Coupling

- **Suppose that** $\Psi(x, y) = xy$, $\mu(x) = I(x \in [0, 1])$,
 $\nu(y) = e^{-y}I(y > 0)$.
- Solve primal by sampling: Let $\{X_i^n\}_{i=1}^n$ and $\{Y_i^n\}_{i=1}^n$ both i.i.d. from μ and ν , respectively.

$$F_{\mu_n}(x) = \frac{1}{n} \sum_{i=1}^n I(X_i^n \leq x), \quad F_{\nu_n}(y) = \frac{1}{n} \sum_{j=1}^n I(Y_j^n \leq y)$$

- Consider

$$\begin{aligned} & \max_{\pi(x_i^n, x_j^n) \geq 0} \sum_{i,j} \Psi(x_i^n, y_j^n) \pi(x_i^n, y_j^n) \\ & \sum_j \pi(x_i^n, y_j^n) = \frac{1}{n} \quad \forall x_i, \quad \sum_i \pi(x_i^n, y_j^n) = \frac{1}{n} \quad \forall y_j. \end{aligned}$$

Solving for Optimal Transport Coupling

- **Suppose that** $\Psi(x, y) = xy$, $\mu(x) = I(x \in [0, 1])$,
 $\nu(y) = e^{-y}I(y > 0)$.
- Solve primal by sampling: Let $\{X_i^n\}_{i=1}^n$ and $\{Y_i^n\}_{i=1}^n$ both i.i.d. from μ and ν , respectively.

$$F_{\mu_n}(x) = \frac{1}{n} \sum_{i=1}^n I(X_i^n \leq x), \quad F_{\nu_n}(y) = \frac{1}{n} \sum_{j=1}^n I(Y_j^n \leq y)$$

- Consider

$$\begin{aligned} & \max_{\pi(x_i^n, x_j^n) \geq 0} \sum_{i,j} \Psi(x_i^n, y_j^n) \pi(x_i^n, y_j^n) \\ & \sum_j \pi(x_i^n, y_j^n) = \frac{1}{n} \quad \forall x_i, \quad \sum_i \pi(x_i^n, y_j^n) = \frac{1}{n} \quad \forall y_j. \end{aligned}$$

- **Clearly, simply sort and match is the solution!**

Solving for Optimal Transport Coupling

- Think of $Y_j^n = -\log(1 - U_j^n) = F_v^{-1}(U_j^n)$ for U_j^n s i.i.d. uniform(0, 1).

Solving for Optimal Transport Coupling

- Think of $Y_j^n = -\log(1 - U_j^n) = F_v^{-1}(U_j^n)$ for U_j^n s i.i.d. uniform(0, 1).
- The j -th order statistic $X_{(j)}^n$ is matched to $Y_{(j)}^n$.

Solving for Optimal Transport Coupling

- Think of $Y_j^n = -\log(1 - U_j^n) = F_v^{-1}(U_j^n)$ for U_j^n s i.i.d. uniform(0, 1).
- The j -th order statistic $X_{(j)}^n$ is matched to $Y_{(j)}^n$.
- As $n \rightarrow \infty$, $X_{(nt)}^n \rightarrow t$, so $Y_{(nt)}^n \rightarrow -\log(1 - t)$.

Solving for Optimal Transport Coupling

- Think of $Y_j^n = -\log(1 - U_j^n) = F_v^{-1}(U_j^n)$ for U_j^n s i.i.d. uniform(0, 1).
- The j -th order statistic $X_{(j)}^n$ is matched to $Y_{(j)}^n$.
- As $n \rightarrow \infty$, $X_{(nt)}^n \rightarrow t$, so $Y_{(nt)}^n \rightarrow -\log(1 - t)$.
- Thus, the optimal coupling as $n \rightarrow \infty$ is $X = U$ and $Y = -\log(1 - U)$ (comonotonic coupling).

Solving for Optimal Transport Coupling

- Think of $Y_j^n = -\log(1 - U_j^n) = F_v^{-1}(U_j^n)$ for U_j^n s i.i.d. uniform(0, 1).
- The j -th order statistic $X_{(j)}^n$ is matched to $Y_{(j)}^n$.
- As $n \rightarrow \infty$, $X_{(nt)}^n \rightarrow t$, so $Y_{(nt)}^n \rightarrow -\log(1 - t)$.
- Thus, the optimal coupling as $n \rightarrow \infty$ is $X = U$ and $Y = -\log(1 - U)$ (comonotonic coupling).
- In general, the optimal coupling is $X = F_\mu^{-1}(U)$ and $Y = F_v^{-1}(U)$.

Identities for Wasserstein Distances

- Comonotonic coupling is the solution if $\partial_{x,y}^2 \Psi(x, y) \geq 0$ - supermodularity:

$$\Psi(x \vee x', y \vee y') + \Psi(x \wedge x', y \wedge y') \geq \Psi(x, y) + \Psi(x', y')$$

Identities for Wasserstein Distances

- Comonotonic coupling is the solution if $\partial_{x,y}^2 \Psi(x, y) \geq 0$ - supermodularity:

$$\Psi(x \vee x', y \vee y') + \Psi(x \wedge x', y \wedge y') \geq \Psi(x, y) + \Psi(x', y')$$

- Or, for costs $c(x, y) = -\Psi(x, y)$, if $\partial_{x,y}^2 c(x, y) \leq 0$ (submodularity).

Identities for Wasserstein Distances

- Comonotonic coupling is the solution if $\partial_{x,y}^2 \Psi(x, y) \geq 0$ - supermodularity:

$$\Psi(x \vee x', y \vee y') + \Psi(x \wedge x', y \wedge y') \geq \Psi(x, y) + \Psi(x', y')$$

- Or, for costs $c(x, y) = -\Psi(x, y)$, if $\partial_{x,y}^2 c(x, y) \leq 0$ (submodularity).
- **Corollary:** Suppose $c(x, y) = |x - y|$ then $X = F_\mu^{-1}(U)$ and $Y = F_\nu^{-1}(U)$ thus

$$\begin{aligned} D_c(F_\mu, F_\nu) &= \int_0^1 |F_\mu^{-1}(u) - F_\nu^{-1}(u)| du \\ &= \int_{-\infty}^{\infty} |F_\mu(x) - F_\nu(x)| dx. \end{aligned}$$

Identities for Wasserstein Distances

- Comonotonic coupling is the solution if $\partial_{x,y}^2 \Psi(x, y) \geq 0$ - supermodularity:

$$\Psi(x \vee x', y \vee y') + \Psi(x \wedge x', y \wedge y') \geq \Psi(x, y) + \Psi(x', y')$$

- Or, for costs $c(x, y) = -\Psi(x, y)$, if $\partial_{x,y}^2 c(x, y) \leq 0$ (submodularity).
- **Corollary:** Suppose $c(x, y) = |x - y|$ then $X = F_\mu^{-1}(U)$ and $Y = F_\nu^{-1}(U)$ thus

$$\begin{aligned} D_c(F_\mu, F_\nu) &= \int_0^1 |F_\mu^{-1}(u) - F_\nu^{-1}(u)| du \\ &= \int_{-\infty}^{\infty} |F_\mu(x) - F_\nu(x)| dx. \end{aligned}$$

- Similar identities are common for Wasserstein distances...

Interesting Insight on Salary Effects

- In equilibrium, by the envelope theorem

$$\dot{\beta}^*(y) = \frac{d}{dy} \sup_x [\Psi(x, y) - \alpha^*(x)] = \frac{\partial}{\partial y} \Psi(x_y, y) = x_y$$

$$\dot{\alpha}^*(x) = \frac{\partial}{\partial x} \Psi(x, y_x) = y_x = F_v^{-1}(F_\mu(x)).$$

Interesting Insight on Salary Effects

- In equilibrium, by the envelope theorem

$$\dot{\beta}^*(y) = \frac{d}{dy} \sup_x [\Psi(x, y) - \alpha^*(x)] = \frac{\partial}{\partial y} \Psi(x_y, y) = x_y$$

$$\dot{\alpha}^*(x) = \frac{\partial}{\partial x} \Psi(x, y_x) = y_x = F_v^{-1}(F_\mu(x)).$$

- We also know that $y = -\log(1-x)$, or $x = 1 - \exp(-y)$

$$\beta^*(y) = y + \exp(-y) - 1 + \beta^*(0).$$

$$\alpha^*(x) + \beta^*(-\log(1-x)) = xy.$$

Interesting Insight on Salary Effects

- In equilibrium, by the envelope theorem

$$\dot{\beta}^*(y) = \frac{d}{dy} \sup_x [\Psi(x, y) - \alpha^*(x)] = \frac{\partial}{\partial y} \Psi(x_y, y) = x_y$$

$$\dot{\alpha}^*(x) = \frac{\partial}{\partial x} \Psi(x, y_x) = y_x = F_v^{-1}(F_\mu(x)).$$

- We also know that $y = -\log(1-x)$, or $x = 1 - \exp(-y)$

$$\beta^*(y) = y + \exp(-y) - 1 + \beta^*(0).$$

$$\alpha^*(x) + \beta^*(-\log(1-x)) = xy.$$

- What if $\Psi(x, y) \rightarrow \Psi(x, y) + f(x)$? (i.e. productivity changes).

Interesting Insight on Salary Effects

- In equilibrium, by the envelope theorem

$$\dot{\beta}^*(y) = \frac{d}{dy} \sup_x [\Psi(x, y) - \alpha^*(x)] = \frac{\partial}{\partial y} \Psi(x_y, y) = x_y$$

$$\dot{\alpha}^*(x) = \frac{\partial}{\partial x} \Psi(x, y_x) = y_x = F_v^{-1}(F_\mu(x)).$$

- We also know that $y = -\log(1-x)$, or $x = 1 - \exp(-y)$

$$\beta^*(y) = y + \exp(-y) - 1 + \beta^*(0).$$

$$\alpha^*(x) + \beta^*(-\log(1-x)) = xy.$$

- What if $\Psi(x, y) \rightarrow \Psi(x, y) + f(x)$? (i.e. productivity changes).
- *Answer: salaries increase if $f(\cdot)$ is increasing.*

Additional properties of Optimal Transport Solutions:
Kantorovich-Rubinstein Duality and Wasserstein GAN.

Back to Wasserstein Distances

- Consider the case $c(x, y) = d(x, y)$.

Back to Wasserstein Distances

- Consider the case $c(x, y) = d(x, y)$.
- Recall dual

$$\begin{aligned} \max E_{\mu} \alpha(X) - E_{\nu} \beta(Y) \\ \text{s.t. } \alpha(x) - \beta(y) \leq d(x, y) \quad \forall x, y \in \mathcal{S}. \end{aligned}$$

Back to Wasserstein Distances

- Consider the case $c(x, y) = d(x, y)$.
- Recall dual

$$\begin{aligned} \max E_{\mu} \alpha(X) - E_{\nu} \beta(Y) \\ \text{s.t. } \alpha(x) - \beta(y) \leq d(x, y) \quad \forall x, y \in \mathcal{S}. \end{aligned}$$

- Note that given β , we should pick

$$\alpha(x) = \beta^d(x) := \inf_y \{\beta(y) + d(x, y)\},$$

similarly once $\alpha(\cdot)$ is chosen, we could improve by picking

$$\beta^{dd}(y) = \sup_x \{\beta^d(x) - d(x, y)\}.$$

Transforms are Lipschitz

- Moreover, observe that $\beta^d(\cdot)$ is 1-Lipschitz

$$\begin{aligned}\beta^d(x) &= \inf_y \{\beta(y) + d(x, y)\} \leftarrow \text{recall def} \\ \beta^d(x) - \beta^d(x') &= \beta(y_x) + d(x, y_x) \\ &\quad - \beta(y_{x'}) - d(x, y_{x'}) \\ &\leq d(x, y_{x'}) - d(x, y_{x'}) \leq d(x, x').\end{aligned}$$

Transforms are Lipschitz

- Moreover, observe that $\beta^d(\cdot)$ is 1-Lipschitz

$$\begin{aligned}\beta^d(x) &= \inf_y \{\beta(y) + d(x, y)\} \leftarrow \text{recall def} \\ \beta^d(x) - \beta^d(x') &= \beta(y_x) + d(x, y_x) \\ &\quad - \beta(y_{x'}) - d(x, y_{x'}) \\ &\leq d(x, y_{x'}) - d(x, y_{x'}) \leq d(x, x').\end{aligned}$$

- Same argument is true for $\beta^{dd}(y)$.

The Transform of a Lipschitz Function is the Function Itself

- Moreover,

$$\beta^d(x) := \inf_y \{\beta(y) + d(x, y)\} \leq \beta(x)$$

and if β is 1-Lipschitz (meaning $|\beta(x) - \beta(y)| \leq d(x, y)$) then

$$\begin{aligned} \beta^d(x) - \beta(x) &= \inf_y \{d(x, y) + \beta(y) - \beta(x)\} \\ &\geq \inf_y \{d(x, y) - d(x, y)\} = 0. \end{aligned}$$

The Transform of a Lipschitz Function is the Function Itself

- Moreover,

$$\beta^d(x) := \inf_y \{\beta(y) + d(x, y)\} \leq \beta(x)$$

and if β is 1-Lipschitz (meaning $|\beta(x) - \beta(y)| \leq d(x, y)$) then

$$\begin{aligned} \beta^d(x) - \beta(x) &= \inf_y \{d(x, y) + \beta(y) - \beta(x)\} \\ &\geq \inf_y \{d(x, y) - d(x, y)\} = 0. \end{aligned}$$

- Consequently, if β is 1-Lipschitz $\beta = \beta^d \dots$ So, the dual can be simplified.

- Original Dual:

$$\begin{aligned} \max E_{\mu} \alpha (X) - E_{\nu} \beta (Y) \\ \text{s.t. } \alpha (x) - \beta (y) \leq d (x, y) \quad \forall \quad x, y \in \mathcal{S} . \end{aligned}$$

- Original Dual:

$$\begin{aligned} \max E_{\mu} \alpha (X) - E_{\nu} \beta (Y) \\ \text{s.t. } \alpha (x) - \beta (y) \leq d (x, y) \quad \forall \quad x, y \in \mathcal{S} . \end{aligned}$$

- Simplified Dual (called Kantorovich duality result):

$$\begin{aligned} \max E_{\mu} \alpha (X) - E_{\nu} \alpha (Y) \\ \text{s.t. } \alpha \text{ is 1-Lipschitz .} \end{aligned}$$

- Original Dual:

$$\begin{aligned} \max E_{\mu} \alpha (X) - E_{\nu} \beta (Y) \\ \text{s.t. } \alpha (x) - \beta (y) \leq d (x, y) \quad \forall \quad x, y \in \mathcal{S} . \end{aligned}$$

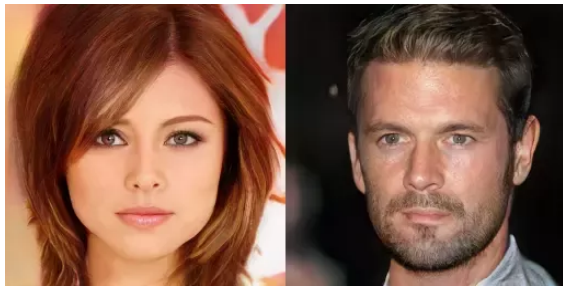
- Simplified Dual (called Kantorovich duality result):

$$\begin{aligned} \max E_{\mu} \alpha (X) - E_{\nu} \alpha (Y) \\ \text{s.t. } \alpha \text{ is 1-Lipschitz .} \end{aligned}$$

- This is the basis for so-called Wasserstein GAN (Generative Adversarial Networks) – popular in artificial intelligence.

A Quick Discussion on Wasserstein GAN

- Have you even thought about how to generate a "face" at random? (<https://github.com/hindupuravinash/the-gan-zoo>).



A Quick Discussion on Wasserstein GAN

- What's the formulation

$$\min_{\theta < \text{NN parameter}} D_d(v_\theta, \mu_n),$$

where μ_n represents the empirical measure of images.

A Quick Discussion on Wasserstein GAN

- What's the formulation

$$\min_{\theta < \text{NN parameter}} D_d(v_{\theta}, \mu_n),$$

where μ_n represents the empirical measure of images.

- $v_{\theta}(\cdot)$ is a probability measure generated by a Neural Network (NN), from initial random noise

A Quick Discussion on Wasserstein GAN

- What's the formulation

$$\min_{\theta < \text{NN parameter}} D_d(v_{\theta}, \mu_n),$$

where μ_n represents the empirical measure of images.

- $v_{\theta}(\cdot)$ is a probability measure generated by a Neural Network (NN), from initial random noise
- θ represents the parameter of the network.

A Quick Discussion on Wasserstein GAN

- What's the formulation

$$\min_{\theta < \text{NN parameter}} D_d(v_\theta, \mu_n),$$

where μ_n represents the empirical measure of images.

- $v_\theta(\cdot)$ is a probability measure generated by a Neural Network (NN), from initial random noise
- θ represents the parameter of the network.
- By duality

$$\min_{\theta < \text{NN parameter}} \sup_{\alpha \text{-1-Lip}} \{E_{v_\theta}(\alpha(X)) - E_{\mu_n}(\alpha(Y))\}.$$

A Quick Discussion on Wasserstein GAN

- What's the formulation

$$\min_{\theta < \text{NN parameter}} D_d(v_\theta, \mu_n),$$

where μ_n represents the empirical measure of images.

- $v_\theta(\cdot)$ is a probability measure generated by a Neural Network (NN), from initial random noise
- θ represents the parameter of the network.
- By duality

$$\min_{\theta < \text{NN parameter}} \sup_{\alpha \text{-1-Lip}} \{E_{v_\theta}(\alpha(X)) - E_{\mu_n}(\alpha(Y))\}.$$

- Use another Neural Network to parameterize α (i.e. a 1-Lip function).

A Quick Discussion on Wasserstein GAN

- What's the formulation

$$\min_{\theta < \text{NN parameter}} D_d(v_\theta, \mu_n),$$

where μ_n represents the empirical measure of images.

- $v_\theta(\cdot)$ is a probability measure generated by a Neural Network (NN), from initial random noise
- θ represents the parameter of the network.
- By duality

$$\min_{\theta < \text{NN parameter}} \sup_{\alpha \text{-1-Lip}} \{E_{v_\theta}(\alpha(X)) - E_{\mu_n}(\alpha(Y))\}.$$

- Use another Neural Network to parameterize α (i.e. a 1-Lip function).
- Apply automatic differentiation to compute gradients & run stochastic gradient descent.

Optimal Transport with Quadratic Costs

- The case $c(x, y) = \|x - y\|_2^2 / 2$ is important because of its intuitive appeal and its theoretical properties.

Optimal Transport with Quadratic Costs

- The case $c(x, y) = \|x - y\|_2^2 / 2$ is important because of its intuitive appeal and its theoretical properties.
- We consider

$$D_c(\mu, \nu) = \min_{\pi} \{2^{-1} E_{\pi} \|X - Y\|_2^2 : \pi_X = \mu \text{ and } \pi_Y = \nu\}.$$

Optimal Transport with Quadratic Costs

- The case $c(x, y) = \|x - y\|_2^2 / 2$ is important because of its intuitive appeal and its theoretical properties.
- We consider

$$D_c(\mu, \nu) = \min_{\pi} \{2^{-1} E_{\pi} \|X - Y\|_2^2 : \pi_X = \mu \text{ and } \pi_Y = \nu\}.$$

- We assume that $E \|X\|_2^2 + E \|Y\|_2^2 < \infty$.

Optimal Transport with Quadratic Costs

- The case $c(x, y) = \|x - y\|_2^2 / 2$ is important because of its intuitive appeal and its theoretical properties.
- We consider

$$D_c(\mu, \nu) = \min_{\pi} \{2^{-1} E_{\pi} \|X - Y\|_2^2 : \pi_X = \mu \text{ and } \pi_Y = \nu\}.$$

- We assume that $E \|X\|_2^2 + E \|Y\|_2^2 < \infty$.
- So, the problem is equivalent to

$$\max_{\pi} \{E_{\pi} (X^T Y) : \pi_X = \mu \text{ and } \pi_Y = \nu\}.$$

Optimal Transport with Quadratic Costs

- The case $c(x, y) = \|x - y\|_2^2 / 2$ is important because of its intuitive appeal and its theoretical properties.
- We consider

$$D_c(\mu, \nu) = \min_{\pi} \{2^{-1} E_{\pi} \|X - Y\|_2^2 : \pi_X = \mu \text{ and } \pi_Y = \nu\}.$$

- We assume that $E \|X\|_2^2 + E \|Y\|_2^2 < \infty$.
- So, the problem is equivalent to

$$\max_{\pi} \{E_{\pi} (X^T Y) : \pi_X = \mu \text{ and } \pi_Y = \nu\}.$$

- The dual is

$$\min \{E_{\mu} \alpha(X) + E_{\nu} \beta(Y) : \alpha(x) + \beta(y) \geq x^T y \text{ for } x, y \in S\}.$$

Optimal Transport with Quadratic Costs

- The dual is

$$\min\{E_{\mu}\alpha(X) + E_{\nu}\beta(Y) : \alpha(x) + \beta(y) \geq x^T y \text{ for } x, y \in S\}.$$

Optimal Transport with Quadratic Costs

- The dual is

$$\min\{E_{\mu}\alpha(X) + E_{\nu}\beta(Y) : \alpha(x) + \beta(y) \geq x^T y \text{ for } x, y \in S\}.$$

- Note now that given $\alpha(x)$ we improve the objective function choosing

$$\alpha^*(y) = \sup_x [x^T y - \alpha(x)],$$

which is convex.

Optimal Transport with Quadratic Costs

- The dual is

$$\min\{E_{\mu}\alpha(X) + E_{\nu}\beta(Y) : \alpha(x) + \beta(y) \geq x^T y \text{ for } x, y \in S\}.$$

- Note now that given $\alpha(x)$ we improve the objective function choosing

$$\alpha^*(y) = \sup_x [x^T y - \alpha(x)],$$

which is convex.

- So, in the end the dual is simplified to

$$\min\{E_{\mu}\alpha(X) + E_{\nu}\alpha^*(Y) : \alpha \text{ convex}\}.$$

Optimal Transport with Quadratic Costs

- Now, our goal is to characterize the optimal solution of the primal and dual problems.

Optimal Transport with Quadratic Costs

- Now, our goal is to characterize the optimal solution of the primal and dual problems.
- Suppose that μ has a density with respect to the Lebesgue measure.

Optimal Transport with Quadratic Costs

- Now, our goal is to characterize the optimal solution of the primal and dual problems.
- Suppose that μ has a density with respect to the Lebesgue measure.
- By complementary slackness

$$\alpha(x) + \alpha^*(y) = x^T y - \pi^* \text{ a.s.}$$

Optimal Transport with Quadratic Costs

- Now, our goal is to characterize the optimal solution of the primal and dual problems.
- Suppose that μ has a density with respect to the Lebesgue measure.
- By complementary slackness

$$\alpha(x) + \alpha^*(y) = x^T y - \pi^* \text{ a.s.}$$

- But given x , equality holds if and only if $y \in \partial a(x) \leftarrow$ subdifferential (by convex analysis).

Optimal Transport with Quadratic Costs

- Now, our goal is to characterize the optimal solution of the primal and dual problems.
- Suppose that μ has a density with respect to the Lebesgue measure.
- By complementary slackness

$$\alpha(x) + \alpha^*(y) = x^T y - \pi^* \text{ a.s.}$$

- But given x , equality holds if and only if $y \in \partial a(x) \leftarrow$ subdifferential (by convex analysis).
- Similarly, given y , if and only if $x \in \partial \alpha^*(y)$.

Optimal Transport with Quadratic Costs

- Now, our goal is to characterize the optimal solution of the primal and dual problems.
- Suppose that μ has a density with respect to the Lebesgue measure.
- By complementary slackness

$$\alpha(x) + \alpha^*(y) = x^T y - \pi^* \text{ a.s.}$$

- But given x , equality holds if and only if $y \in \partial \alpha(x) \leftarrow$ subdifferential (by convex analysis).
- Similarly, given y , if and only if $x \in \partial \alpha^*(y)$.
- But by Rademacher's theorem $\alpha(\cdot)$ is differentiable almost everywhere. So, given $X \sim \mu$, $Y = \nabla \alpha(X)$.

Optimal Transport with Quadratic Costs

- Consequently, this establishes Brennier's Theorem: If $c(x, y) = \|x - y\|_2^2 / 2$ then the optimal coupling

$$(X, Y) = (X, \nabla \alpha(X)),$$

where $\alpha(\cdot)$ is convex.

Optimal Transport with Quadratic Costs

- Consequently, this establishes Brennier's Theorem: If $c(x, y) = \|x - y\|_2^2 / 2$ then the optimal coupling

$$(X, Y) = (X, \nabla\alpha(X)),$$

where $\alpha(\cdot)$ is convex.

- The optimal $\nabla\alpha(\cdot)$ is unique almost surely: Suppose $\nabla\bar{\alpha}$ is another solution to the dual.

Optimal Transport with Quadratic Costs

- Consequently, this establishes Brennier's Theorem: If $c(x, y) = \|x - y\|_2^2 / 2$ then the optimal coupling

$$(X, Y) = (X, \nabla \alpha(X)),$$

where $\alpha(\cdot)$ is convex.

- The optimal $\nabla \alpha(\cdot)$ is unique almost surely: Suppose $\nabla \bar{\alpha}$ is another solution to the dual.
- Then consider the couplings $(X, \nabla \alpha(X))$ and $(X, \nabla \bar{\alpha}(X))$ we have that for almost every x

$$\alpha(x) + \alpha^*(\nabla \bar{\alpha}(x)) = x^T \nabla \bar{\alpha}(x)$$

(by complementary slackness).

Optimal Transport with Quadratic Costs

- Consequently, this establishes Brennier's Theorem: If $c(x, y) = \|x - y\|_2^2 / 2$ then the optimal coupling

$$(X, Y) = (X, \nabla \alpha(X)),$$

where $\alpha(\cdot)$ is convex.

- The optimal $\nabla \alpha(\cdot)$ is unique almost surely: Suppose $\nabla \bar{\alpha}$ is another solution to the dual.
- Then consider the couplings $(X, \nabla \alpha(X))$ and $(X, \nabla \bar{\alpha}(X))$ we have that for almost every x

$$\alpha(x) + \alpha^*(\nabla \bar{\alpha}(x)) = x^T \nabla \bar{\alpha}(x)$$

(by complementary slackness).

- Therefore $\nabla \bar{\alpha}(x) \in \partial \alpha(x)$ and by Rademacher $\nabla \bar{\alpha} = \nabla \alpha$ almost surely.

Optimal Transport with Quadratic Costs

- Example: Suppose that $X \sim N(0, I)$ and $Y \sim N(0, \Sigma)$ we want to transport X into Y optimally using the cost $c(x, y) = \|x - y\|_2^2 / 2$.

Optimal Transport with Quadratic Costs

- Example: Suppose that $X \sim N(0, I)$ and $Y \sim N(0, \Sigma)$ we want to transport X into Y optimally using the cost $c(x, y) = \|x - y\|_2^2 / 2$.
- We postulate that $\nabla \alpha(x) = Ax$ where A is positive definite.

Optimal Transport with Quadratic Costs

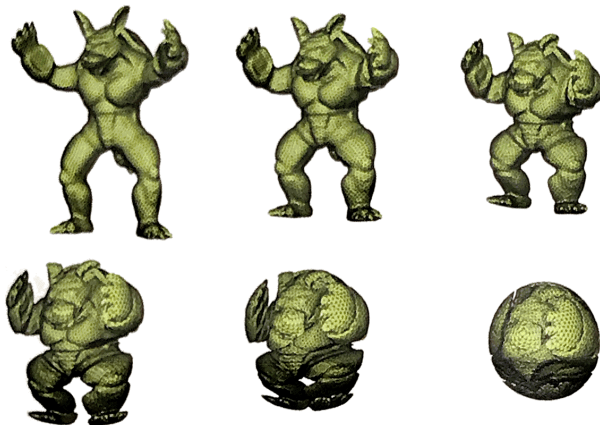
- Example: Suppose that $X \sim N(0, I)$ and $Y \sim N(0, \Sigma)$ we want to transport X into Y optimally using the cost $c(x, y) = \|x - y\|_2^2 / 2$.
- We postulate that $\nabla \alpha(x) = Ax$ where A is positive definite.
- **So, we must have that $A \cdot A = \Sigma$, the solution is that A is the polar factorization of Σ .**

Optimal Transport with Quadratic Costs

- Example: Suppose that $X \sim N(0, I)$ and $Y \sim N(0, \Sigma)$ we want to transport X into Y optimally using the cost $c(x, y) = \|x - y\|_2^2 / 2$.
- We postulate that $\nabla \alpha(x) = Ax$ where A is positive definite.
- **So, we must have that $A \cdot A = \Sigma$, the solution is that A is the polar factorization of Σ .**
- *From here it is easy to derive what the general optimal transport map is between two Gaussians (try this as an exercise).*

Illustration of Optimal Transport in Image Analysis

- Santambrogio (2010)'s illustration



The discussion is based on
B. & Murthy (2016)

<https://arxiv.org/abs/1604.01446>.

<https://pubsonline.informs.org/doi/abs/10.1287/moor.2018.0936?journalCod>

A Distributionally Robust Performance Analysis

- We are often interested in

$$E_{P_{true}}(f(X))$$

for a complex model P_{true} .

A Distributionally Robust Performance Analysis

- We are often interested in

$$E_{P_{true}} (f (X))$$

for a complex model P_{true} .

- Moreover, we wish to optimize, namely

$$\min_{\theta} E_{P_{true}} (h (X, \theta)).$$

A Distributionally Robust Performance Analysis

- We are often interested in

$$E_{P_{true}} (f (X))$$

for a complex model P_{true} .

- Moreover, we wish to optimize, namely

$$\min_{\theta} E_{P_{true}} (h (X, \theta)).$$

- Model P_{true} might be unknown or too difficult to work with.

A Distributionally Robust Performance Analysis

- We are often interested in

$$E_{P_{true}} (f (X))$$

for a complex model P_{true} .

- Moreover, we wish to optimize, namely

$$\min_{\theta} E_{P_{true}} (h (X, \theta)).$$

- Model P_{true} might be unknown or too difficult to work with.
- So, we introduce a proxy P_0 which provides a good trade-off between tractability and model fidelity (e.g. Brownian motion for random walk approximations).

A Distributionally Robust Performance Analysis

- For $f(\cdot)$ upper semicontinuous with $E_{P_0} |f(X)| < \infty$

$$\sup E_P (f(Y)) \\ D_c(P, P_0) \leq \delta ,$$

X takes values on a Polish space and $c(\cdot)$ is lower semi-continuous.

A Distributionally Robust Performance Analysis

- For $f(\cdot)$ upper semicontinuous with $E_{P_0} |f(X)| < \infty$

$$\sup E_P (f(Y)) \\ D_c(P, P_0) \leq \delta ,$$

X takes values on a Polish space and $c(\cdot)$ is lower semi-continuous.

- Also an infinite dimensional linear program

$$\begin{aligned} & \sup \int_{\mathcal{X} \times \mathcal{Y}} f(y) \pi(dx, dy) \\ & \text{s.t. } \int_{\mathcal{X} \times \mathcal{Y}} c(x, y) \pi(dx, dy) \leq \delta \\ & \int_{\mathcal{Y}} \pi(dx, dy) = P_0(dx) . \end{aligned}$$

- Formal duality:

$$\begin{aligned} \text{Dual} &= \inf_{\lambda \geq 0, \alpha} \left\{ \lambda \delta + \int \alpha(x) P_0(dx) \right\} \\ &\quad \lambda c(x, y) + \alpha(x) \geq f(y). \end{aligned}$$

A Distributionally Robust Performance Analysis

- Formal duality:

$$\begin{aligned} \text{Dual} &= \inf_{\lambda \geq 0, \alpha} \left\{ \lambda \delta + \int \alpha(x) P_0(dx) \right\} \\ &\quad \lambda c(x, y) + \alpha(x) \geq f(y). \end{aligned}$$

- B. & Murthy (2016) - *No duality gap*:

$$\text{Dual} = \inf_{\lambda \geq 0} \left[\lambda \delta + E_0 \left(\sup_y \{f(y) - \lambda c(X, y)\} \right) \right].$$

A Distributionally Robust Performance Analysis

- Formal duality:

$$\begin{aligned} \text{Dual} = \inf_{\lambda \geq 0, \alpha} & \left\{ \lambda \delta + \int \alpha(x) P_0(dx) \right\} \\ & \lambda c(x, y) + \alpha(x) \geq f(y). \end{aligned}$$

- B. & Murthy (2016) - *No duality gap*:

$$\text{Dual} = \inf_{\lambda \geq 0} \left[\lambda \delta + E_0 \left(\sup_y \{f(y) - \lambda c(X, y)\} \right) \right].$$

- *We refer to this as RoPA Duality in this talk.*

A Distributionally Robust Performance Analysis

- Formal duality:

$$\begin{aligned} \text{Dual} = \inf_{\lambda \geq 0, \alpha} & \left\{ \lambda \delta + \int \alpha(x) P_0(dx) \right\} \\ & \lambda c(x, y) + \alpha(x) \geq f(y). \end{aligned}$$

- B. & Murthy (2016) - *No duality gap*:

$$\text{Dual} = \inf_{\lambda \geq 0} \left[\lambda \delta + E_0 \left(\sup_y \{f(y) - \lambda c(X, y)\} \right) \right].$$

- *We refer to this as RoPA Duality in this talk.*
- Let us consider an important case first: $f(y) = I(y \in A)$ & $c(x, x) = 0$.

A Distributionally Robust Performance Analysis

- So, if $f(y) = I(y \in A)$ and $c_A(X) = \inf\{y \in A : c(x, y)\}$, then

$$Dual = \inf_{\lambda \geq 0} \left[\lambda \delta + E_0 (1 - \lambda c_A(X))^+ \right] = P_0(c_A(X) \leq 1/\lambda_*).$$

A Distributionally Robust Performance Analysis

- So, if $f(y) = I(y \in A)$ and $c_A(X) = \inf\{y \in A : c(x, y)\}$, then

$$Dual = \inf_{\lambda \geq 0} \left[\lambda \delta + E_0 (1 - \lambda c_A(X))^+ \right] = P_0(c_A(X) \leq 1/\lambda_*).$$

- If $c_A(X)$ is continuous under P_0 & $E_0(c_A(X)) \geq \delta$, then

$$\delta = E_0 [c_A(X) I(c_A(X) \leq 1/\lambda_*)].$$

Example: Model Uncertainty in Bankruptcy Calculations

- $R(t)$ = the reserve (perhaps multiple lines) at time t .

Example: Model Uncertainty in Bankruptcy Calculations

- $R(t)$ = the reserve (perhaps multiple lines) at time t .
- Bankruptcy probability (in finite time horizon T)

$$u_T = P_{true} (R(t) \in B \text{ for some } t \in [0, T]).$$

Example: Model Uncertainty in Bankruptcy Calculations

- $R(t)$ = the reserve (perhaps multiple lines) at time t .
- Bankruptcy probability (in finite time horizon T)

$$u_T = P_{true} (R(t) \in B \text{ for some } t \in [0, T]).$$

- B is a set which models bankruptcy.

Example: Model Uncertainty in Bankruptcy Calculations

- $R(t)$ = the reserve (perhaps multiple lines) at time t .
- Bankruptcy probability (in finite time horizon T)

$$u_T = P_{true} (R(t) \in B \text{ for some } t \in [0, T]).$$

- B is a set which models bankruptcy.
- **Problem:** Model (P_{true}) may be complex, intractable or simply unknown...

A Distributionally Robust Risk Analysis Formulation

- **Our solution:** Estimate u_T by solving

$$\sup_{D_c(P_0, P) \leq \delta} P_{true} (R(t) \in B \text{ for some } t \in [0, T]),$$

where P_0 is a *suitable* model.

A Distributionally Robust Risk Analysis Formulation

- **Our solution:** Estimate u_T by solving

$$\sup_{D_c(P_0, P) \leq \delta} P_{true} (R(t) \in B \text{ for some } t \in [0, T]),$$

where P_0 is a *suitable* model.

- $P_0 =$ proxy for P_{true} .

A Distributionally Robust Risk Analysis Formulation

- **Our solution:** Estimate u_T by solving

$$\sup_{D_c(P_0, P) \leq \delta} P_{true} (R(t) \in B \text{ for some } t \in [0, T]),$$

where P_0 is a *suitable* model.

- $P_0 =$ proxy for P_{true} .
- P_0 right trade-off between fidelity and tractability.

A Distributionally Robust Risk Analysis Formulation

- **Our solution:** Estimate u_T by solving

$$\sup_{D_c(P_0, P) \leq \delta} P_{true} (R(t) \in B \text{ for some } t \in [0, T]),$$

where P_0 is a *suitable* model.

- $P_0 =$ proxy for P_{true} .
- P_0 right trade-off between fidelity and tractability.
- δ is the distributional uncertainty size.

A Distributionally Robust Risk Analysis Formulation

- **Our solution:** Estimate u_T by solving

$$\sup_{D_c(P_0, P) \leq \delta} P_{true} (R(t) \in B \text{ for some } t \in [0, T]),$$

where P_0 is a *suitable* model.

- $P_0 =$ proxy for P_{true} .
- P_0 right trade-off between fidelity and tractability.
- δ is the distributional uncertainty size.
- $D_c(\cdot)$ is the distributional uncertainty region.

Desirable Elements of Distributionally Robust Formulation

- Would like $D_c(\cdot)$ to have wide flexibility (even non-parametric).

Desirable Elements of Distributionally Robust Formulation

- Would like $D_c(\cdot)$ to have wide flexibility (even non-parametric).
- Want optimization to be tractable.

Desirable Elements of Distributionally Robust Formulation

- Would like $D_c(\cdot)$ to have wide flexibility (even non-parametric).
- Want optimization to be tractable.
- *Want to preserve advantages of using P_0 .*

Desirable Elements of Distributionally Robust Formulation

- Would like $D_c(\cdot)$ to have wide flexibility (even non-parametric).
- Want optimization to be tractable.
- *Want to preserve advantages of using P_0 .*
- Want a way to estimate δ .

Connections to Distributionally Robust Optimization

- Standard choices based on divergence (such as Kullback-Leibler) - Hansen & Sargent (2016)

$$D(\nu || \mu) = E_{\nu} \left(\log \left(\frac{d\nu}{d\mu} \right) \right).$$

- Standard choices based on divergence (such as Kullback-Leibler) - Hansen & Sargent (2016)

$$D(v||\mu) = E_v \left(\log \left(\frac{dv}{d\mu} \right) \right).$$

- Robust Optimization: Ben-Tal, El Ghaoui, Nemirovski (2009).

Connections to Distributionally Robust Optimization

- Standard choices based on divergence (such as Kullback-Leibler) - Hansen & Sargent (2016)

$$D(\nu || \mu) = E_{\nu} \left(\log \left(\frac{d\nu}{d\mu} \right) \right).$$

- Robust Optimization: Ben-Tal, El Ghaoui, Nemirovski (2009).
- **Big problem: Absolute continuity may typically be violated...**

Connections to Distributionally Robust Optimization

- Standard choices based on divergence (such as Kullback-Leibler) - Hansen & Sargent (2016)

$$D(v||\mu) = E_v \left(\log \left(\frac{dv}{d\mu} \right) \right).$$

- Robust Optimization: Ben-Tal, El Ghaoui, Nemirovski (2009).
- **Big problem: Absolute continuity may typically be violated...**
- Think of using Brownian motion as a proxy model for $R(t)$...

- Standard choices based on divergence (such as Kullback-Leibler) - Hansen & Sargent (2016)

$$D(v||\mu) = E_v \left(\log \left(\frac{dv}{d\mu} \right) \right).$$

- Robust Optimization: Ben-Tal, El Ghaoui, Nemirovski (2009).
- **Big problem: Absolute continuity may typically be violated...**
- Think of using Brownian motion as a proxy model for $R(t)$...
- **Optimal transport is a natural option!**

Application 1: Back to Classical Risk Problem

- Suppose that

$$\begin{aligned}c(x, y) &= d_J(x(\cdot), y(\cdot)) = \text{Skorokhod } J_1 \text{ metric.} \\ &= \inf_{\phi(\cdot) \text{ bijection}} \left\{ \sup_{t \in [0,1]} |x(t) - y(\phi(t))|, \sup_{t \in [0,1]} |\phi(t) - t| \right\}.\end{aligned}$$

Application 1: Back to Classical Risk Problem

- Suppose that

$$\begin{aligned}c(x, y) &= d_J(x(\cdot), y(\cdot)) = \text{Skorokhod } J_1 \text{ metric.} \\ &= \inf_{\phi(\cdot) \text{ bijection}} \left\{ \sup_{t \in [0,1]} |x(t) - y(\phi(t))|, \sup_{t \in [0,1]} |\phi(t) - t| \right\}.\end{aligned}$$

- If $R(t) = b - Z(t)$, then ruin during time interval $[0, 1]$ is

$$B_b = \left\{ R(\cdot) : 0 \geq \inf_{t \in [0,1]} R(t) \right\} = \left\{ Z(\cdot) : b \leq \sup_{t \in [0,1]} Z(t) \right\}.$$

Application 1: Back to Classical Risk Problem

- Suppose that

$$\begin{aligned}c(x, y) &= d_J(x(\cdot), y(\cdot)) = \text{Skorokhod } J_1 \text{ metric.} \\ &= \inf_{\phi(\cdot) \text{ bijection}} \left\{ \sup_{t \in [0,1]} |x(t) - y(\phi(t))|, \sup_{t \in [0,1]} |\phi(t) - t| \right\}.\end{aligned}$$

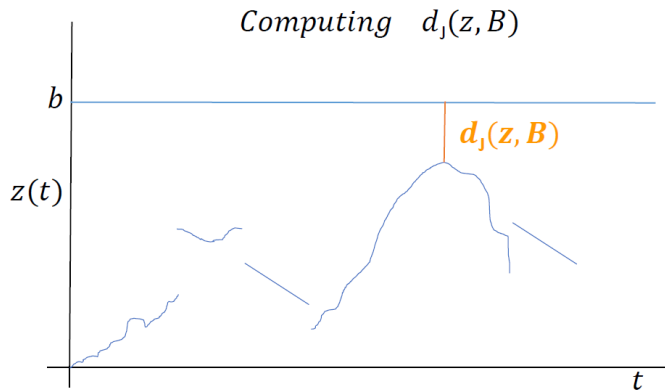
- If $R(t) = b - Z(t)$, then ruin during time interval $[0, 1]$ is

$$B_b = \left\{ R(\cdot) : 0 \geq \inf_{t \in [0,1]} R(t) \right\} = \left\{ Z(\cdot) : b \leq \sup_{t \in [0,1]} Z(t) \right\}.$$

- **Let $P_0(\cdot)$ be the Wiener measure want to compute**

$$\sup_{D_c(P_0, P) \leq \delta} P(Z \in B_b).$$

Application 1: Computing Distance to Bankruptcy



- **So:** $\{c_{B_b}(Z) \leq 1/\lambda_*\} = \{\sup_{t \in [0,1]} Z(t) \geq b - 1/\lambda_*\}$, and

$$\sup_{D_c(P_0, P) \leq \delta} P(Z \in B_b) = P_0 \left(\sup_{t \in [0,1]} Z(t) \geq b - 1/\lambda_* \right).$$

Application 1: Computing Uncertainty Size

- Note **any coupling** π so that $\pi_X = P_0$ and $\pi_Y = P$ satisfies

$$D_c(P_0, P) \leq E_\pi [c(X, Y)] \approx \delta.$$

Application 1: Computing Uncertainty Size

- Note **any coupling** π so that $\pi_X = P_0$ and $\pi_Y = P$ satisfies

$$D_c(P_0, P) \leq E_\pi [c(X, Y)] \approx \delta.$$

- So use any coupling between *evidence* and P_0 or expert knowledge.

Application 1: Computing Uncertainty Size

- Note **any coupling** π so that $\pi_X = P_0$ and $\pi_Y = P$ satisfies

$$D_c(P_0, P) \leq E_\pi [c(X, Y)] \approx \delta.$$

- So use any coupling between *evidence* and P_0 or expert knowledge.
- We discuss choosing δ non-parametrically momentarily.

Application 1: Illustration of Coupling

- Given arrivals and claim sizes let $Z(t) = m_2^{-1/2} \sum_{k=1}^{N(t)} (X_k - m_1)$

Algorithm 1 To embed the process $(Z(t) : t \geq 0)$ in Brownian motion $(B(t) : t \geq 0)$

Given: Brownian motion $B(t)$, moment m_1 and independent realizations of claim sizes X_1, X_2, \dots

Initialize $\tau_0 := 0$ and $\Psi_0 := 0$. For $j \geq 1$, recursively define,

$$\tau_{j+1} := \inf \left\{ s \geq \tau_j : \sup_{\tau_j \leq r \leq s} B_r - B_s = X_{j+1} \right\}, \text{ and } \Psi_j := \Psi_{j-1} + X_j.$$

Define the auxiliary processes

$$\tilde{S}(t) := \sum_{j>0} \sup_{\tau_j \leq s \leq t} B(s) \mathbf{1}(\tau_j \leq t < \tau_{j+1}) \text{ and } \tilde{N}(t) := \sum_{j \geq 0} \Psi_j \mathbf{1}(\tau_j \leq t < \tau_{j+1}).$$

Let $A(t) := \tilde{N}(t) + \tilde{S}(t)$, and identify the time change $\sigma(t) := \inf\{s : A(s) = m_1 t\}$. Next, take the time changed version $Z(t) := \tilde{S}(\sigma(t))$.

Replace $Z(t)$ by $-Z(t)$ and $B(t)$ by $-B(t)$.

Application 1: Illustration of Coupling

- Given arrivals and claim sizes let $Z(t) = m_2^{-1/2} \sum_{k=1}^{N(t)} (X_k - m_1)$

Algorithm 1 To embed the process $(Z(t) : t \geq 0)$ in Brownian motion $(B(t) : t \geq 0)$

Given: Brownian motion $B(t)$, moment m_1 and independent realizations of claim sizes X_1, X_2, \dots

Initialize $\tau_0 := 0$ and $\Psi_0 := 0$. For $j \geq 1$, recursively define,

$$\tau_{j+1} := \inf \left\{ s \geq \tau_j : \sup_{\tau_j \leq r \leq s} B_r - B_s = X_{j+1} \right\}, \text{ and } \Psi_j := \Psi_{j-1} + X_j.$$

Define the auxiliary processes

$$\tilde{S}(t) := \sum_{j>0} \sup_{\tau_j \leq s \leq t} B(s) \mathbf{1}(\tau_j \leq t < \tau_{j+1}) \text{ and } \tilde{N}(t) := \sum_{j \geq 0} \Psi_j \mathbf{1}(\tau_j \leq t < \tau_{j+1}).$$

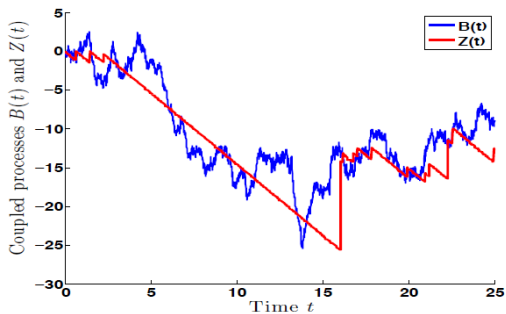
Let $A(t) := \tilde{N}(t) + \tilde{S}(t)$, and identify the time change $\sigma(t) := \inf\{s : A(s) = m_1 t\}$. Next, take the time changed version $Z(t) := \tilde{S}(\sigma(t))$.

Replace $Z(t)$ by $-Z(t)$ and $B(t)$ by $-B(t)$.

- See also Fomivoch, Gonzalez-Cazares, Ivanovs (2021).

Application 1: Coupling in Action

FIGURE 4. A coupled path output by Algorithm 1



Application 1: Numerical Example

- Assume Poisson arrivals.
- *Pareto claim sizes with index 2.2* – $(P(V > t) = 1/(1 + t)^{2.2})$.
- Cost $c(x, y) = d_J(x, y)^2$ ← note power of 2.
- Used Algorithm 1 to calibrate (estimating means and variances from data).

b	$\frac{P_0(\text{Ruin})}{P_{true}(\text{Ruin})}$	$\frac{P_{robust}^*(\text{Ruin})}{P_{true}(\text{Ruin})}$
100	1.07×10^{-1}	12.28
150	2.52×10^{-4}	10.65
200	5.35×10^{-8}	10.80
250	1.15×10^{-12}	10.98

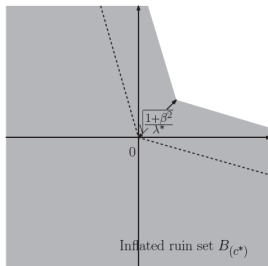
- See also Birghila, Aigner, Engelke (2021)

Additional Applications: Multidimensional Ruin Problems

- <https://arxiv.org/abs/1604.01446> contains more applications.

Additional Applications: Multidimensional Ruin Problems

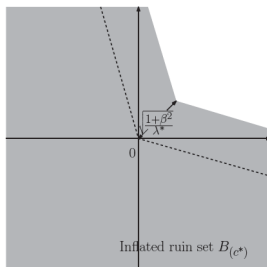
- <https://arxiv.org/abs/1604.01446> contains more applications.
- Control: $\min_{\theta} \sup_{P: D(P, P_0) \leq \delta} E[L(\theta, Z)]$ ← robust optimal reinsurance.



(b) Computation of worst-case ruin using the baseline measure

Additional Applications: Multidimensional Ruin Problems

- <https://arxiv.org/abs/1604.01446> contains more applications.
- Control: $\min_{\theta} \sup_{P:D(P,P_0)\leq\delta} E[L(\theta, Z)]$ ← robust optimal reinsurance.

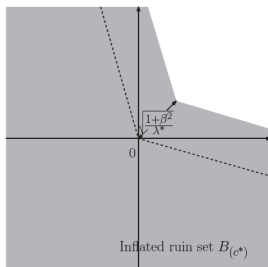


(b) Computation of worst-case ruin using the baseline measure

- Multidimensional risk processes (explicit evaluation of $c_B(x)$ for d_J metric).

Additional Applications: Multidimensional Ruin Problems

- <https://arxiv.org/abs/1604.01446> contains more applications.
- Control: $\min_{\theta} \sup_{P:D(P,P_0)\leq\delta} E[L(\theta, Z)]$ ← robust optimal reinsurance.

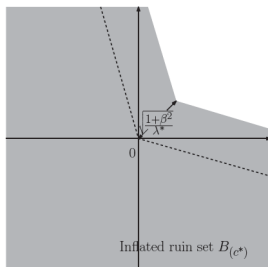


(b) Computation of worst-case ruin using the baseline measure

- Multidimensional risk processes (explicit evaluation of $c_B(x)$ for d_J metric).
- **Key insight: Geometry of target set often remains largely the same!**

Additional Applications: Multidimensional Ruin Problems

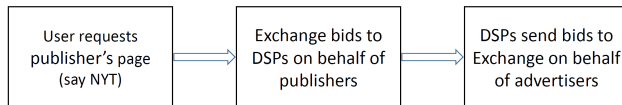
- <https://arxiv.org/abs/1604.01446> contains more applications.
- Control: $\min_{\theta} \sup_{P:D(P,P_0)\leq\delta} E[L(\theta, Z)]$ ← robust optimal reinsurance.



(b) Computation of worst-case ruin using the baseline measure

- Multidimensional risk processes (explicit evaluation of $c_B(x)$ for d_J metric).
- **Key insight: Geometry of target set often remains largely the same!**
- See also Engelke and Ivanovs (2017)

Background: (Very) Simplified version of Demand Side Platforms (DSPs)



Goal of DSP: Maximize revenue on behalf of advertisers

A Bit of Background on Online Advertising

- Until recently, most exchanges operated using second price auctions.

A Bit of Background on Online Advertising

- Until recently, most exchanges operated using second price auctions.
- The optimal bidding policy in second price auctions is to bid truthfully.

A Bit of Background on Online Advertising

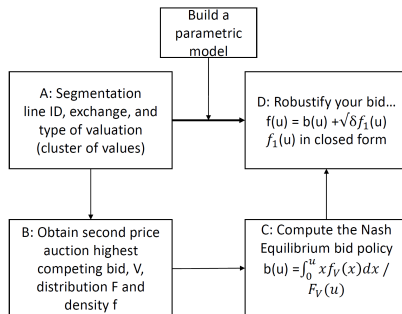
- Until recently, most exchanges operated using second price auctions.
- The optimal bidding policy in second price auctions is to bid truthfully.
- Now, first price auction exchanges have become popular.

A Bit of Background on Online Advertising

- Until recently, most exchanges operated using second price auctions.
- The optimal bidding policy in second price auctions is to bid truthfully.
- Now, first price auction exchanges have become popular.
- How to transfer information from second-price exchanges into first-price exchanges?

Summary of blue print

A → B → C → D



- $U_i = (\text{dlls}/1000)$ value of the item in auction i if we win. We write $U_i = u_i$ when value is given.
- $b_i = (\text{dlls}/1000)$ is what we bid in the i -th auction (cost in 1st price auction).
- $V_i = (\text{dlls}/1000)$ is the highest competing bid in the i -th auction.
- $f_{V_i} =$ the probability density function of V_i .
- $F_{V_i} =$ the cumulative distribution function of V_i .

Model and Performance Measure

- A Simplified Model:

$$\max_{\{b_1, \dots, b_n\}} \frac{1}{n} \sum_{i=1}^n (u_i - b_i) P(V_i \leq b_i | U_i = u_i),$$

where n is the number of auctions in a given time period, for instance, a day.

Model and Performance Measure

- A Simplified Model:

$$\max_{\{b_1, \dots, b_n\}} \frac{1}{n} \sum_{i=1}^n (u_i - b_i) P(V_i \leq b_i | U_i = u_i),$$

where n is the number of auctions in a given time period, for instance, a day.

- Assume auctions are split according to segments, such as line and exchange, to induce homogeneity.

Model and Performance Measure

- A Simplified Model:

$$\max_{\{b_1, \dots, b_n\}} \frac{1}{n} \sum_{i=1}^n (u_i - b_i) P(V_i \leq b_i | U_i = u_i),$$

where n is the number of auctions in a given time period, for instance, a day.

- Assume auctions are split according to segments, such as line and exchange, to induce homogeneity.
- *Homogeneity*: For each $i \neq j$

$$P(V_i \leq b | U_i = u) = P(V_j \leq b | U_j = u).$$

Model and Performance Measure

- A Simplified Model:

$$\max_{\{b_1, \dots, b_n\}} \frac{1}{n} \sum_{i=1}^n (u_i - b_i) P(V_i \leq b_i | U_i = u_i),$$

where n is the number of auctions in a given time period, for instance, a day.

- Assume auctions are split according to segments, such as line and exchange, to induce homogeneity.
- *Homogeneity*: For each $i \neq j$

$$P(V_i \leq b | U_i = u) = P(V_j \leq b | U_j = u).$$

- Under homogeneity it suffices to solve

$$\max_b (u - b) P(V \leq b | U = u).$$

Model and Performance Measure

- A Simplified Model:

$$\max_{\{b_1, \dots, b_n\}} \frac{1}{n} \sum_{i=1}^n (u_i - b_i) P(V_i \leq b_i | U_i = u_i),$$

where n is the number of auctions in a given time period, for instance, a day.

- Assume auctions are split according to segments, such as line and exchange, to induce homogeneity.
- *Homogeneity*: For each $i \neq j$

$$P(V_i \leq b | U_i = u) = P(V_j \leq b | U_j = u).$$

- Under homogeneity it suffices to solve

$$\max_b (u - b) P(V \leq b | U = u).$$

- *Also assume conditional independence.*

Dealing with Dependence

- Setting the derivative with respect to b equal to zero yields

$$b = u - F_{V|U=u}(b) / f_{V|U=u}(b).$$

Dealing with Dependence

- Setting the derivative with respect to b equal to zero yields

$$b = u - F_{V|U=u}(b) / f_{V|U=u}(b).$$

- *Challenge:* The quantity

$$F_{V|U=u}(\cdot) \quad \text{and} \quad f_{V|U=u}(\cdot)$$

are virtually impossible to estimate in a first price auction setting.

Dealing with Dependence

- Setting the derivative with respect to b equal to zero yields

$$b = u - F_{V|U=u}(b) / f_{V|U=u}(b).$$

- *Challenge:* The quantity

$$F_{V|U=u}(\cdot) \quad \text{and} \quad f_{V|U=u}(\cdot)$$

are virtually impossible to estimate in a first price auction setting.

- *Virtually ONLY solution:* Assume that V and U are conditionally independent given some other observable factor Θ .

Dealing with Dependence

- Setting the derivative with respect to b equal to zero yields

$$b = u - F_{V|U=u}(b) / f_{V|U=u}(b).$$

- *Challenge:* The quantity

$$F_{V|U=u}(\cdot) \quad \text{and} \quad f_{V|U=u}(\cdot)$$

are virtually impossible to estimate in a first price auction setting.

- *Virtually ONLY solution:* Assume that V and U are conditionally independent given some other observable factor Θ .
- For example: Θ is a value type (i.e. $\Theta = k \Leftrightarrow U \in \mathcal{A}_k$) = segmentation across values (there are only a few segments).

Dealing with Dependence

- Setting the derivative with respect to b equal to zero yields

$$b = u - F_{V|U=u}(b) / f_{V|U=u}(b).$$

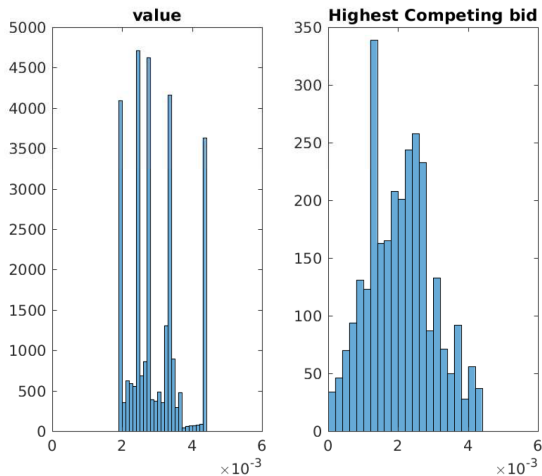
- *Challenge:* The quantity

$$F_{V|U=u}(\cdot) \quad \text{and} \quad f_{V|U=u}(\cdot)$$

are virtually impossible to estimate in a first price auction setting.

- *Virtually ONLY solution:* Assume that V and U are conditionally independent given some other observable factor Θ .
- For example: Θ is a value type (i.e. $\Theta = k \Leftrightarrow U \in \mathcal{A}_k$) = segmentation across values (there are only a few segments).
- We go back to this in part II)...

Inducing Homogeneity and Conditional Independence



Quantifying Model Misspecifications

- Even if two exchanges run under second price auctions, their competitive landscapes may be different.

Quantifying Model Misspecifications

- Even if two exchanges run under second price auctions, their competitive landscapes may be different.
- So, if \bar{V} is taken from exchange X , we need to recognize the possibility of model error.

Quantifying Model Misspecifications

- Even if two exchanges run under second price auctions, their competitive landscapes may be different.
- So, if \bar{V} is taken from exchange X , we need to recognize the possibility of model error.
- We do this by introducing a metric to compare CDFs, say F and G

$$D(F, G) = \int_{-\infty}^{\infty} |F(x) - G(x)| dx.$$

Quantifying Model Misspecifications

- Even if two exchanges run under second price auctions, their competitive landscapes may be different.
- So, if \bar{V} is taken from exchange X , we need to recognize the possibility of model error.
- We do this by introducing a metric to compare CDFs, say F and G

$$D(F, G) = \int_{-\infty}^{\infty} |F(x) - G(x)| dx.$$

- It turns out that

$$D(F, G) = \min\{E(|X - Y|) \text{ over all joint distributions such that } X \text{ has CDF } F \text{ and } Y \text{ has CDF } G\}.$$

Quantifying Model Misspecifications

- We now want

$$\max_b \min_{D(F, F_V) \leq \delta} (u - b) F(b).$$

Quantifying Model Misspecifications

- We now want

$$\max_b \min_{D(F, F_V) \leq \delta} (u - b) F(b).$$

- If we write $\bar{F}(x) = 1 - F(x) = P(V > x)$, then the inner minimization is equivalent to

$$\max_{D(F, F_V) \leq \delta} \bar{F}(b) = \max_{D(F, F_V) \leq \delta} P_F(V > b) = P_F(V > b - \lambda_b).$$

Quantifying Model Misspecifications

- We now want

$$\max_b \min_{D(F, F_V) \leq \delta} (u - b) F(b).$$

- If we write $\bar{F}(x) = 1 - F(x) = P(V > x)$, then the inner minimization is equivalent to

$$\max_{D(F, F_V) \leq \delta} \bar{F}(b) = \max_{D(F, F_V) \leq \delta} P_F(V > b) = P_F(V > b - \lambda_b).$$

- Let $\lambda = \lambda_b \geq 0$ be a Lagrange multiplier, the "worst case distribution" is

$$\begin{aligned} V^* &= V \cdot I(V > b) + b \cdot I(b - \lambda < V \leq b) \\ &\quad + V \cdot I(V \leq b - \lambda). \end{aligned}$$

Quantifying Model Mispredictions

- We now want

$$\max_b \min_{D(F, F_V) \leq \delta} (u - b) F(b).$$

- If we write $\bar{F}(x) = 1 - F(x) = P(V > x)$, then the inner minimization is equivalent to

$$\max_{D(F, F_V) \leq \delta} \bar{F}(b) = \max_{D(F, F_V) \leq \delta} P_F(V > b) = P_F(V > b - \lambda_b).$$

- Let $\lambda = \lambda_b \geq 0$ be a Lagrange multiplier, the "worst case distribution" is

$$\begin{aligned} V^* &= V \cdot I(V > b) + b \cdot I(b - \lambda < V \leq b) \\ &\quad + V \cdot I(V \leq b - \lambda). \end{aligned}$$

- Intuitively: re-arrange V as cheaply as possible to produce V^* so that $V^* > b$ happens (λ computed to satisfy cost constraint).

Quantifying Model Misspecifications

- Conclusion: We are trying to find the (Nash Equilibrium) policy $b^*(u) = f(u)$ so

$$\begin{aligned} & \max_b \min_{D(F, F_{\bar{V}}) \leq \delta} (u - b) F_{\bar{V}}(f^{-1}(b)) \\ &= \max_b (u - b) F_{\bar{V}}\left(f^{-1}(b) - \lambda_{f^{-1}(b)}\right). \end{aligned}$$

Quantifying Model Misspecifications

- Conclusion: We are trying to find the (Nash Equilibrium) policy $b^*(u) = f(u)$ so

$$\begin{aligned} & \max_b \min_{D(F, F_{\bar{V}}) \leq \delta} (u - b) F_{\bar{V}}(f^{-1}(b)) \\ &= \max_b (u - b) F_{\bar{V}}\left(f^{-1}(b) - \lambda_{f^{-1}(b)}\right). \end{aligned}$$

- Optimizing over $b(\cdot)$ we obtain

$$b(u) = \frac{\int_0^u x f_{\bar{V}}(x - \lambda_x) (1 - \dot{\lambda}(x)) dx}{F_{\bar{V}}(u - \lambda_u)},$$

with

$$\int_{u - \lambda_u}^u (u - v) f_{\bar{V}}(v) dv = \delta.$$

Approximate Distributionally Robust Equilibrium Bidding Policies

- While the previous equations can be solved numerically, they may be a bit cumbersome to implement.

Approximate Distributionally Robust Equilibrium Bidding Policies

- While the previous equations can be solved numerically, they may be a bit cumbersome to implement.
- So, we provide an asymptotic expansion as $\delta \rightarrow 0$.

Approximate Distributionally Robust Equilibrium Bidding Policies

- While the previous equations can be solved numerically, they may be a bit cumbersome to implement.
- So, we provide an asymptotic expansion as $\delta \rightarrow 0$.
- This leads to a bidding strategy of the form

$$b_\delta(u) = b_0(u) + \delta^{1/2} b_1(u) + O(\delta),$$

where

$$b_0(u) = E(\bar{V} | \bar{V} \leq u) = \int_0^u x f_{\bar{V}}(x) dx / F_{\bar{V}}(u)$$

and

$$b_1(u) = \frac{\sqrt{2}}{F_{\bar{V}}(u)} \left(\int_0^u \sqrt{f_{\bar{V}}(x)} dx - \frac{f_{\bar{V}}(u)}{F_{\bar{V}}(u)} \int_0^u F_{\bar{V}}(x) dx \right).$$

- Example 3: Back to logistic model

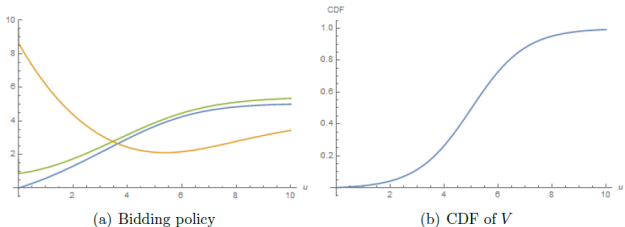
Example

- Example 3: Back to logistic model
- $P(\bar{V} \leq x) = (1 + \exp(-xc)) / (1 + \exp(a - xc))$ for $a \in R, c > 0$.

Example

- Example 3: Back to logistic model
- $P(\bar{V} \leq x) = (1 + \exp(-xc)) / (1 + \exp(a - xc))$ for $a \in R, c > 0$.
- $a = 5, c = 1$ and $\delta = .01$ (figures in \$/1000)

We show the bidding policy and CDF for $a = 5, c = 1, \delta = 0.01$ in the following plot.



So, now we want to add a player optimizing a decision and play the game:

$$\min_{\theta} \max_{D(P, P_n) \leq \delta} E(I(X, \theta)).$$

Based on: Robust Wasserstein Profile Inference (B., Murthy & Kang '16)

<https://arxiv.org/abs/1610.05627>

<https://www.cambridge.org/core/journals/journal-of-applied-probability/article/abs/robust-wasserstein-profile-inference-and-applications-to-machine-learning>

- Consider estimating $\beta_* \in R^m$ in linear regression

$$Y_i = \beta X_i + e_i,$$

where $\{(Y_i, X_i)\}_{i=1}^n$ are data points.

- Consider estimating $\beta_* \in R^m$ in linear regression

$$Y_i = \beta X_i + e_i,$$

where $\{(Y_i, X_i)\}_{i=1}^n$ are data points.

- Optimal Least Squares approach consists in estimating β_* via

$$\min_{\beta} E_{P_n} \left[\left(Y - \beta^T X \right)^2 \right] = \min_{\beta} \frac{1}{n} \sum_{i=1}^n \left(Y_i - \beta^T X_i \right)^2$$

- Consider estimating $\beta_* \in R^m$ in linear regression

$$Y_i = \beta X_i + e_i,$$

where $\{(Y_i, X_i)\}_{i=1}^n$ are data points.

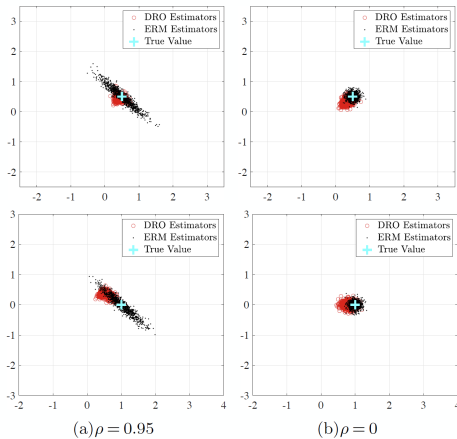
- Optimal Least Squares approach consists in estimating β_* via

$$\min_{\beta} E_{P_n} \left[\left(Y - \beta^T X \right)^2 \right] = \min_{\beta} \frac{1}{n} \sum_{i=1}^n \left(Y_i - \beta^T X_i \right)^2$$

- Apply the distributionally robust estimator based on optimal transport.

Applying Distributionally Robust Optimization in Linear Regression

Estimation of θ_* with DRO (\circ) and without DRO (\circ)



Theorem (B., Kang, Murthy (2016)) Suppose that

$$c((x, y), (x', y')) = \begin{cases} \|x - x'\|_q^2 & \text{if } y = y' \\ \infty & \text{if } y \neq y' \end{cases} .$$

Then, if $1/p + 1/q = 1$

$$\max_{P: D_c(P, P_n) \leq \delta} E_P^{1/2} \left((Y - \beta^T X)^2 \right) = E_{P_n}^{1/2} \left[(Y - \beta^T X)^2 \right] + \sqrt{\delta} \|\beta\|_p .$$

Remark 1: This is sqrt-Lasso (Belloni et al. (2011)).

- Classical classification model:

$$P(Y = 1|X) = \frac{\exp(\beta^T X)}{1 + \exp(\beta^T X)} = \frac{1}{\exp(-\beta^T X) + 1}$$

$$P(Y = -1|X) = \frac{1}{1 + \exp(\beta^T X)}$$

- Classical classification model:

$$P(Y = 1|X) = \frac{\exp(\beta^T X)}{1 + \exp(\beta^T X)} = \frac{1}{\exp(-\beta^T X) + 1}$$

$$P(Y = -1|X) = \frac{1}{1 + \exp(\beta^T X)}$$

- The likelihood of (y, x) is:

$$-\log\left(1 + \exp\left(-y\beta^T x\right)\right)$$

- Therefore, given $\{(y_i, x_i)\}_{i=1}^n$ maximum likelihood is equivalent to

$$\max_{\beta} - \sum_{i=1}^n \log \left(1 + \exp \left(-y_i \beta^T x_i \right) \right).$$

- Therefore, given $\{(y_i, x_i)\}_{i=1}^n$ maximum likelihood is equivalent to

$$\max_{\beta} - \sum_{i=1}^n \log \left(1 + \exp \left(-y_i \beta^T x_i \right) \right).$$

- Also equivalent to

$$\begin{aligned} & \min_{\beta} E_{P_n} \left[\log \left(1 + \exp \left(-Y \beta^T X \right) \right) \right] \\ &= \min_{\beta} \frac{1}{n} \sum_{i=1}^n \log \left(1 + \exp \left(-y_i \beta^T x_i \right) \right). \end{aligned}$$

Regularized Logistic Regression

Theorem (B., Kang, Murthy (2016)) Suppose that

$$c((x, y), (x', y')) = \begin{cases} \|x - x'\|_q & \text{if } y = y' \\ \infty & \text{if } y \neq y' \end{cases} .$$

Then,

$$\begin{aligned} & \sup_{P: \mathcal{D}_c(P, P_n) \leq \delta} E_P \left[\log(1 + e^{-Y\beta^T X}) \right] \\ &= E_{P_n} \left[\log(1 + e^{-Y\beta^T X}) \right] + \delta \|\beta\|_p . \end{aligned}$$

Remark 1: First studied via an approximation in Esfahani and Kuhn (2015).

Theorem (B., Kang, Murthy (2016)) Suppose that

$$c((x, y), (x', y')) = \begin{cases} \|x - x'\|_q & \text{if } y = y' \\ \infty & \text{if } y \neq y' \end{cases}.$$

Then,

$$\begin{aligned} & \sup_{P: \mathcal{D}_c(P, P_n) \leq \delta} E_P \left[\left(1 - Y \beta^T X \right)^+ \right] \\ &= E_{P_n} \left[\left(1 - Y \beta^T X \right)^+ \right] + \delta \|\beta\|_p. \end{aligned}$$

Unification and Extensions of Regularized Estimators

- Distributionally Robust Optimization using Optimal Transport recovers many other estimators...

Unification and Extensions of Regularized Estimators

- Distributionally Robust Optimization using Optimal Transport recovers many other estimators...
- *Group Lasso*: B., & Kang (2016):
<https://arxiv.org/abs/1705.04241>

Unification and Extensions of Regularized Estimators

- Distributionally Robust Optimization using Optimal Transport recovers many other estimators...
- *Group Lasso*: B., & Kang (2016):
<https://arxiv.org/abs/1705.04241>
- *Generalized adaptive ridge*: B., Kang, Murthy, Zhang (2017):
<https://arxiv.org/abs/1705.07152>

Unification and Extensions of Regularized Estimators

- Distributionally Robust Optimization using Optimal Transport recovers many other estimators...
- *Group Lasso*: B., & Kang (2016):
<https://arxiv.org/abs/1705.04241>
- *Generalized adaptive ridge*: B., Kang, Murthy, Zhang (2017):
<https://arxiv.org/abs/1705.07152>
- Semisupervised learning: B., and Kang (2016):
<https://arxiv.org/abs/1702.08848>

Unification and Extensions of Regularized Estimators

- Distributionally Robust Optimization using Optimal Transport recovers many other estimators...
- *Group Lasso*: B., & Kang (2016):
<https://arxiv.org/abs/1705.04241>
- *Generalized adaptive ridge*: B., Kang, Murthy, Zhang (2017):
<https://arxiv.org/abs/1705.07152>
- Semisupervised learning: B., and Kang (2016):
<https://arxiv.org/abs/1702.08848>
- See the excellent tutorials by Kuhn et al (2019) and Rahimian & Mehrotra (2019).

Unification and Extensions of Regularized Estimators

- Distributionally Robust Optimization using Optimal Transport recovers many other estimators...
- *Group Lasso*: B., & Kang (2016):
<https://arxiv.org/abs/1705.04241>
- *Generalized adaptive ridge*: B., Kang, Murthy, Zhang (2017):
<https://arxiv.org/abs/1705.07152>
- Semisupervised learning: B., and Kang (2016):
<https://arxiv.org/abs/1702.08848>
- See the excellent tutorials by Kuhn et al (2019) and Rahimian & Mehrotra (2019).
- Other areas in which optimal transport arises in machine learning

Deep Neural Networks: Adversarial Attacks

- Szegedy, Zaremba, Sutskever, Bruna, Erhan, Goodfellow, and Fergus (2014).



x

“panda”

57.7% confidence

+ .007 ×



$\text{sign}(\nabla_x J(\theta, x, y))$

“nematode”

8.2% confidence

=



$x +$

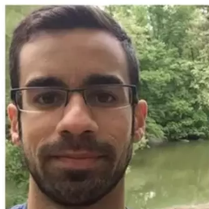
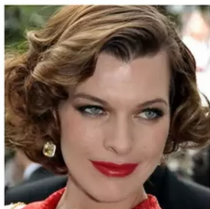
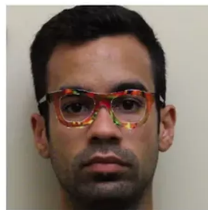
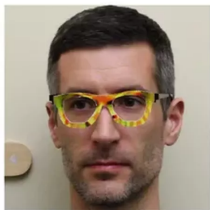
$\epsilon \text{sign}(\nabla_x J(\theta, x, y))$

“gibbon”

99.3 % confidence

Deep Neural Networks: Adversarial Attacks

- Sharif, Bhagavatula, Bauer, and Reiter (2016)



Deep Neural Networks: Adversarial Attacks

- Picture from the BBC

Chinese man caught by facial recognition at pop concert

13 April 2018



Chinese police have used facial recognition technology to locate and arrest a man who was among a crowd of 60,000 concert goers.

How Regularization and Dual Norms Arise?

- Let us work out a simple example...

How Regularization and Dual Norms Arise?

- Let us work out a simple example...
- Recall RoPA Duality: Pick $c((x, y), (x', y')) = \|(x, y) - (x', y')\|_q^2$

$$\begin{aligned} & \max_{P: D_c(P, P_n) \leq \delta} E_P \left(((X, Y) \cdot (\beta, 1))^2 \right) \\ &= \min_{\lambda \geq 0} \left\{ \lambda \delta + E_{P_n} \sup_{(x', y')} \left[((x', y') \cdot (\beta, 1))^2 - \lambda \|(X, Y) - (x', y')\|_q^2 \right] \right\} \end{aligned}$$

How Regularization and Dual Norms Arise?

- Let us work out a simple example...
- Recall RoPA Duality: Pick $c((x, y), (x', y')) = \|(x, y) - (x', y')\|_q^2$

$$\begin{aligned} & \max_{P: D_c(P, P_n) \leq \delta} E_P \left(((X, Y) \cdot (\beta, 1))^2 \right) \\ &= \min_{\lambda \geq 0} \left\{ \lambda \delta + E_{P_n} \sup_{(x', y')} \left[((x', y') \cdot (\beta, 1))^2 - \lambda \|(X, Y) - (x', y')\|_q^2 \right] \right\} \end{aligned}$$

- Let's focus on the inside $E_{P_n} \dots$

How Regularization and Dual Norms Arise?

- Let $\Delta = (X, Y) - (x', y')$

$$\begin{aligned} & \sup_{(x', y')} \left[((x', y') \cdot (\beta, 1))^2 - \lambda \|(X, Y) - (x', y')\|_q^2 \right] \\ = & \sup_{\Delta} \left[((X, Y) \cdot (\beta, 1) - \Delta \cdot (\beta, 1))^2 - \lambda \|\Delta\|_q^2 \right] \\ = & \sup_{\|\Delta\|_q} \left[(|(X, Y) \cdot (\beta, 1)| + \|\Delta\|_q \|(\beta, 1)\|_p)^2 - \lambda \|\Delta\|_q^2 \right] \end{aligned}$$

How Regularization and Dual Norms Arise?

- Let $\Delta = (X, Y) - (x', y')$

$$\begin{aligned} & \sup_{(x', y')} \left[((x', y') \cdot (\beta, 1))^2 - \lambda \|(X, Y) - (x', y')\|_q^2 \right] \\ &= \sup_{\Delta} \left[((X, Y) \cdot (\beta, 1) - \Delta \cdot (\beta, 1))^2 - \lambda \|\Delta\|_q^2 \right] \\ &= \sup_{\|\Delta\|_q} \left[(|(X, Y) \cdot (\beta, 1)| + \|\Delta\|_q \|(\beta, 1)\|_p)^2 - \lambda \|\Delta\|_q^2 \right] \end{aligned}$$

- Last equality uses $z \rightarrow z^2$ is symmetric around origin and $|a \cdot b| \leq \|a\|_p \|b\|_q$.

How Regularization and Dual Norms Arise?

- Let $\Delta = (X, Y) - (x', y')$

$$\begin{aligned} & \sup_{(x', y')} \left[((x', y') \cdot (\beta, 1))^2 - \lambda \|(X, Y) - (x', y')\|_q^2 \right] \\ &= \sup_{\Delta} \left[((X, Y) \cdot (\beta, 1) - \Delta \cdot (\beta, 1))^2 - \lambda \|\Delta\|_q^2 \right] \\ &= \sup_{\|\Delta\|_q} \left[(|(X, Y) \cdot (\beta, 1)| + \|\Delta\|_q \|(\beta, 1)\|_p)^2 - \lambda \|\Delta\|_q^2 \right] \end{aligned}$$

- Last equality uses $z \rightarrow z^2$ is symmetric around origin and $|a \cdot b| \leq \|a\|_p \|b\|_q$.
- Note problem is now one-dimensional (easily computable).

A Fully Worked Out Example: Support Vector Machines

- Use RoPA: with

$$c((x, y), (x', y')) = \|x - x'\|_q I(y = y') + \infty I(y \neq y')$$

$$\sup_{P: \mathcal{D}_c(P, P_n) \leq \delta} E_P \left[\left(1 - Y\beta^T X \right)^+ \right]$$

$$= \min_{\lambda \geq 0} \left[\lambda \delta + E_{P_n} \left\{ \max_x \left(\left(1 - Y\beta^T x \right)^+ - \lambda \|x - X\|_q \right) \right\} \right]$$

$$= \min_{\lambda \geq 0} \left[\lambda \delta + E_{P_n} \left\{ \max_{\Delta} \left(\left(1 - Y\beta^T X - Y\beta^T \Delta \right)^+ - \lambda \|\Delta\|_q \right) \right\} \right]$$

$$= \min_{\lambda \geq 0} \left[\lambda \delta + E_{P_n} \left\{ \max_{\Delta} \left(\left(1 - Y\beta^T X + \|\beta\|_p \|\Delta\|_q \right)^+ - \lambda \|\Delta\|_q \right) \right\} \right]$$

$$= \min_{\lambda \geq \|\beta\|_p} \left[\lambda \delta + E_{P_n} \left\{ \max_{\|\Delta\|_q} \left(\left(1 - Y\beta^T X + \|\beta\|_p \|\Delta\|_q \right)^+ - \lambda \|\Delta\|_q \right) \right\} \right]$$

$$= \min_{\lambda \geq \|\beta\|_p} \left[\lambda \delta + E_{P_n} \left(1 - Y\beta^T X \right)^+ \right] = \lambda \|\beta\|_p + E_{P_n} \left(1 - Y\beta^T X \right)^+$$

Explaining the Adversarial Attacks of Neural Networks

- So, in general

$$c((x, y), (x', y')) = \|x - x'\|_q I(y = y') + \infty I(y \neq y')$$

$$\begin{aligned} & \sup_{P: \mathcal{D}_c(P, P_n) \leq \delta} E_P [I(\theta, Y, X)] \\ &= \min_{\lambda \geq 0} \left[\lambda \delta + E_{P_n} \left\{ \max_x \left(I(\theta, Y, x) - \lambda \|x - X\|_q \right) \right\} \right] \\ &= \min_{\lambda \geq 0} \left[\lambda \delta + E_{P_n} \left\{ \max_{\Delta} \left(I(\theta, Y, X + \Delta) - \lambda \|\Delta\|_q \right) \right\} \right] \\ &= \min_{\lambda \geq 0} \left[\lambda \delta + E_{P_n} \left\{ \max_{\Delta} \left(I(\theta, Y, X + \Delta/\lambda) - \|\Delta\|_q \right) \right\} \right]. \end{aligned}$$

Explaining the Adversarial Attacks of Neural Networks

- So, in general

$$c((x, y), (x', y')) = \|x - x'\|_q I(y = y') + \infty I(y \neq y')$$

$$\begin{aligned} & \sup_{P: \mathcal{D}_c(P, P_n) \leq \delta} E_P [I(\theta, Y, X)] \\ &= \min_{\lambda \geq 0} \left[\lambda \delta + E_{P_n} \left\{ \max_x \left(I(\theta, Y, x) - \lambda \|x - X\|_q \right) \right\} \right] \\ &= \min_{\lambda \geq 0} \left[\lambda \delta + E_{P_n} \left\{ \max_{\Delta} \left(I(\theta, Y, X + \Delta) - \lambda \|\Delta\|_q \right) \right\} \right] \\ &= \min_{\lambda \geq 0} \left[\lambda \delta + E_{P_n} \left\{ \max_{\Delta} \left(I(\theta, Y, X + \Delta/\lambda) - \|\Delta\|_q \right) \right\} \right]. \end{aligned}$$

- If $\delta \approx 0$, then λ is large, so inner maximization

$$\begin{aligned} & \max_{\Delta} \left(I(\theta, Y, X + \Delta/\lambda) - \|\Delta\|_q \right) \\ & \approx I(\theta, Y, X) + \|I_x(\theta, Y, X)\|_p \|\Delta\|_q / \lambda - \|\Delta\|_q \end{aligned}$$

- The worst case perturbation is given by Δ such that

$$l_x(\theta, Y, X) \cdot \Delta / \lambda = \|l_x(\theta, Y, X)\|_p \|\Delta\|_q / \lambda,$$

if $q = \infty$, then $\Delta = c \cdot \text{sign}(l_x(\theta, Y, X))$.

Summary

- The worst case perturbation is given by Δ such that

$$l_x(\theta, Y, X) \cdot \Delta / \lambda = \|l_x(\theta, Y, X)\|_p \|\Delta\|_q / \lambda,$$

if $q = \infty$, then $\Delta = c \cdot \text{sign}(l_x(\theta, Y, X))$.

- So, $\delta \approx 0$ means perturbing by

$$\epsilon \cdot \text{sign}(l_x(\theta, Y, X))$$

for $\epsilon > 0$.

Summary

- The worst case perturbation is given by Δ such that

$$l_x(\theta, Y, X) \cdot \Delta / \lambda = \|l_x(\theta, Y, X)\|_p \|\Delta\|_q / \lambda,$$

if $q = \infty$, then $\Delta = c \cdot \text{sign}(l_x(\theta, Y, X))$.

- So, $\delta \approx 0$ means perturbing by

$$\epsilon \cdot \text{sign}(l_x(\theta, Y, X))$$

for $\epsilon > 0$.

- This explains the nature of the panda example given earlier.

Can We Defend Against Attacks?

- Naturally, it makes sense then to train networks using

$$\begin{aligned} & \min_{\theta} \max_{D(P, P_n) \leq \delta} E_P (I(\theta, Y, X)) \\ = & \min_{\theta} \{ \lambda \delta + E_{P_n} \max_x [I(\theta, Y, x) - \lambda \|x - X\|_q] \}. \end{aligned}$$

Can We Defend Against Attacks?

- Naturally, it makes sense then to train networks using

$$\begin{aligned} & \min_{\theta} \max_{D(P, P_n) \leq \delta} E_P (I(\theta, Y, X)) \\ &= \min_{\theta} \{ \lambda \delta + E_{P_n} \max_x [I(\theta, Y, x) - \lambda \|x - X\|_q] \}. \end{aligned}$$

- This will automatically protect against attacks.

Can We Defend Against Attacks?

- Naturally, it makes sense then to train networks using

$$\begin{aligned} & \min_{\theta} \max_{D(P, P_n) \leq \delta} E_P (I(\theta, Y, X)) \\ &= \min_{\theta} \{ \lambda \delta + E_{P_n} \max_x [I(\theta, Y, x) - \lambda \|x - X\|_q] \}. \end{aligned}$$

- This will automatically protect against attacks.
- This is an active area of research currently.

Can We Defend Against Attacks?

- Naturally, it makes sense then to train networks using

$$\begin{aligned} & \min_{\theta} \max_{D(P, P_n) \leq \delta} E_P (I(\theta, Y, X)) \\ &= \min_{\theta} \{ \lambda \delta + E_{P_n} \max_x [I(\theta, Y, x) - \lambda \|x - X\|_q] \}. \end{aligned}$$

- This will automatically protect against attacks.
- This is an active area of research currently.
- But there may be many possible attacks.

- <https://arxiv.org/abs/1705.07152>: Data-driven chose of $c(\cdot)$.

On Role of Transport Cost...

- <https://arxiv.org/abs/1705.07152>: Data-driven chose of $c(\cdot)$.
- Suppose that $\|x - x'\|_A^2 = (x - x') A (x - x)$ with A positive definite (Mahalanobis distance).

- <https://arxiv.org/abs/1705.07152>: Data-driven chose of $c(\cdot)$.
- Suppose that $\|x - x'\|_A^2 = (x - x')^T A (x - x')$ with A positive definite (Mahalanobis distance).
- Then,

$$\begin{aligned} & \max_{P: D_c(P, P_n) \leq \delta} E_P^{1/2} \left((Y - \beta^T X)^2 \right) \\ &= \min_{\beta} E_{P_n}^{1/2} \left[(Y - \beta^T X)^2 \right] + \sqrt{\delta} \|\beta\|_{A^{-1}}. \end{aligned}$$

- <https://arxiv.org/abs/1705.07152>: Data-driven choice of $c(\cdot)$.
- Suppose that $\|x - x'\|_A^2 = (x - x')^T A (x - x')$ with A positive definite (Mahalanobis distance).
- Then,

$$\begin{aligned} & \max_{P: D_c(P, P_n) \leq \delta} E_P^{1/2} \left(\left(Y - \beta^T X \right)^2 \right) \\ &= \min_{\beta} E_{P_n}^{1/2} \left[\left(Y - \beta^T X \right)^2 \right] + \sqrt{\delta} \|\beta\|_{A^{-1}}. \end{aligned}$$

- *Intuition: Think of A diagonal, encoding inverse variability of X_i s...*

- <https://arxiv.org/abs/1705.07152>: Data-driven choice of $c(\cdot)$.
- Suppose that $\|x - x'\|_A^2 = (x - x')^T A (x - x')$ with A positive definite (Mahalanobis distance).
- Then,

$$\begin{aligned} & \max_{P: D_c(P, P_n) \leq \delta} E_P^{1/2} \left(\left(Y - \beta^T X \right)^2 \right) \\ &= \min_{\beta} E_{P_n}^{1/2} \left[\left(Y - \beta^T X \right)^2 \right] + \sqrt{\delta} \|\beta\|_{A^{-1}}. \end{aligned}$$

- *Intuition: Think of A diagonal, encoding inverse variability of X_i s...*
- **High variability** \longrightarrow **cheap transportation** \longrightarrow **high impact in risk estimation.**

- <https://arxiv.org/abs/1705.07152>: Data-driven chose of $c(\cdot)$.

- <https://arxiv.org/abs/1705.07152>: Data-driven chose of $c(\cdot)$.
- Suppose that $\|x - x'\|_{\Lambda}^2 = (x - x') \Lambda (x - x)$ with Λ positive definite (Mahalanobis distance).

- <https://arxiv.org/abs/1705.07152>: Data-driven choice of $c(\cdot)$.
- Suppose that $\|x - x'\|_{\Lambda}^2 = (x - x')^T \Lambda (x - x')$ with Λ positive definite (Mahalanobis distance).
- Then,

$$\begin{aligned} & \max_{P: D_c(P, P_n) \leq \delta} E_P^{1/2} \left(\left(Y - \beta^T X \right)^2 \right) \\ &= \min_{\beta} E_{P_n}^{1/2} \left[\left(Y - \beta^T X \right)^2 \right] + \sqrt{\delta} \|\beta\|_{\Lambda^{-1}}. \end{aligned}$$

- <https://arxiv.org/abs/1705.07152>: Data-driven choice of $c(\cdot)$.
- Suppose that $\|x - x'\|_{\Lambda}^2 = (x - x')^T \Lambda (x - x')$ with Λ positive definite (Mahalanobis distance).
- Then,

$$\begin{aligned} & \max_{P: D_c(P, P_n) \leq \delta} E_P^{1/2} \left(\left(Y - \beta^T X \right)^2 \right) \\ &= \min_{\beta} E_{P_n}^{1/2} \left[\left(Y - \beta^T X \right)^2 \right] + \sqrt{\delta} \|\beta\|_{\Lambda^{-1}}. \end{aligned}$$

- *Intuition: Think of Λ diagonal, encoding inverse variability of X_i ...*

On Role of Transport Cost...

- <https://arxiv.org/abs/1705.07152>: Data-driven choice of $c(\cdot)$.
- Suppose that $\|x - x'\|_{\Lambda}^2 = (x - x')^T \Lambda (x - x')$ with Λ positive definite (Mahalanobis distance).
- Then,

$$\begin{aligned} & \max_{P: D_c(P, P_n) \leq \delta} E_P^{1/2} \left(\left(Y - \beta^T X \right)^2 \right) \\ &= \min_{\beta} E_{P_n}^{1/2} \left[\left(Y - \beta^T X \right)^2 \right] + \sqrt{\delta} \|\beta\|_{\Lambda^{-1}}. \end{aligned}$$

- *Intuition: Think of Λ diagonal, encoding inverse variability of X_i s...*
- **High variability** \longrightarrow **cheap transportation** \longrightarrow **high impact in risk estimation.**

Based on:

Robust Wasserstein Profile Inference (B., Murthy & Kang '16)

<https://arxiv.org/abs/1610.05627>

Highlight: How to choose size of uncertainty?

Towards an Optimal Choice of Uncertainty Size

- How to choose uncertainty size in a data-driven way?

Towards an Optimal Choice of Uncertainty Size

- How to choose uncertainty size in a data-driven way?
- Once again, consider Lasso as example:

$$\begin{aligned} & \min_{\beta} \max_{P: D_c(P, P_n) \leq \delta} E_P^{1/2} \left((Y - \beta^T X)^2 \right) \\ &= \min_{\beta} E_{P_n}^{1/2} \left[(Y - \beta^T X)^2 \right] + \sqrt{\delta} \|\beta\|_p. \end{aligned}$$

Towards an Optimal Choice of Uncertainty Size

- How to choose uncertainty size in a data-driven way?
- Once again, consider Lasso as example:

$$\begin{aligned} & \min_{\beta} \max_{P: D_c(P, P_n) \leq \delta} E_P^{1/2} \left(\left(Y - \beta^T X \right)^2 \right) \\ &= \min_{\beta} E_{P_n}^{1/2} \left[\left(Y - \beta^T X \right)^2 \right] + \sqrt{\delta} \|\beta\|_p. \end{aligned}$$

- Use left hand side to define a statistical principle to choose δ .

Towards an Optimal Choice of Uncertainty Size

- How to choose uncertainty size in a data-driven way?
- Once again, consider Lasso as example:

$$\begin{aligned} & \min_{\beta} \max_{P: D_c(P, P_n) \leq \delta} E_P^{1/2} \left(\left(Y - \beta^T X \right)^2 \right) \\ &= \min_{\beta} E_{P_n}^{1/2} \left[\left(Y - \beta^T X \right)^2 \right] + \sqrt{\delta} \|\beta\|_p. \end{aligned}$$

- Use left hand side to define a statistical principle to choose δ .
- Important: Optimizing δ is equivalent to optimizing regularization!

Towards an Optimal Choice of Uncertainty Size

- One way to select δ : estimate $D(P_{true}, P_n)$?

Towards an Optimal Choice of Uncertainty Size

- One way to select δ : estimate $D(P_{true}, P_n)$?
- This was advocated and seems natural at first sight... but there is a big problem.

Towards an Optimal Choice of Uncertainty Size

- One way to select δ : estimate $D(P_{true}, P_n)$?
- This was advocated and seems natural at first sight... but there is a big problem.
- Consider the case $c(x, x') = \|x - x'\|_\infty$ by Kantorovich-Rubinstein duality

$$\begin{aligned} D(P_{true}, P_n) &= \sup_{\alpha \in \text{Lip}(1)} E_{P_{true}} \alpha(X) - E_{P_n} \alpha(X) \\ &= \sup_{\alpha \in \text{Lip}(1)} \int \alpha(x) (dP_{true} - dP_n). \end{aligned}$$

Towards an Optimal Choice of Uncertainty Size

- One way to select δ : estimate $D(P_{true}, P_n)$?
- This was advocated and seems natural at first sight... but there is a big problem.
- Consider the case $c(x, x') = \|x - x'\|_\infty$ by Kantorovich-Rubinstein duality

$$\begin{aligned} D(P_{true}, P_n) &= \sup_{\alpha \in \text{Lip}(1)} E_{P_{true}} \alpha(X) - E_{P_n} \alpha(X) \\ &= \sup_{\alpha \in \text{Lip}(1)} \int \alpha(x) (dP_{true} - dP_n). \end{aligned}$$

- The analysis of this object is extensively studied in the theory of Empirical Processes.

Towards an Optimal Choice of Uncertainty Size

- One way to select δ : estimate $D(P_{true}, P_n)$?
- This was advocated and seems natural at first sight... but there is a big problem.
- Consider the case $c(x, x') = \|x - x'\|_\infty$ by Kantorovich-Rubinstein duality

$$\begin{aligned} D(P_{true}, P_n) &= \sup_{\alpha \in \text{Lip}(1)} E_{P_{true}} \alpha(X) - E_{P_n} \alpha(X) \\ &= \sup_{\alpha \in \text{Lip}(1)} \int \alpha(x) (dP_{true} - dP_n). \end{aligned}$$

- The analysis of this object is extensively studied in the theory of Empirical Processes.
- Unfortunately, it turns out that typically $D(P_{true}, P_n) = O(n^{-1/d})$ (Dudley '68) for $d > 2$.

Towards an Optimal Choice of Uncertainty Size

- So, even if statistics for $D(P_{true}, P_n) = O(n^{-1/d})$ are known, this approach would suggest choosing $\delta = cn^{-1/d}$.

Towards an Optimal Choice of Uncertainty Size

- So, even if statistics for $D(P_{true}, P_n) = O(n^{-1/d})$ are known, this approach would suggest choosing $\delta = cn^{-1/d}$.
- But this would imply solving (say for the logistic regression)

$$\min_{\beta} \{ E_{P_n} \left[\log(1 + e^{-Y\beta^T X}) \right] + cn^{-1/d} \|\beta\|_1 \}.$$

Towards an Optimal Choice of Uncertainty Size

- So, even if statistics for $D(P_{true}, P_n) = O(n^{-1/d})$ are known, this approach would suggest choosing $\delta = cn^{-1/d}$.
- But this would imply solving (say for the logistic regression)

$$\min_{\beta} \{ E_{P_n} \left[\log(1 + e^{-Y\beta^T X}) \right] + cn^{-1/d} \|\beta\|_1 \}.$$

- But we know that letting $\delta = 0$ we typically obtain asymptotically normal estimators

$$\beta_n \approx \beta_{true} + n^{-1/2} N(0, \sigma^2).$$

Towards an Optimal Choice of Uncertainty Size

- So, even if statistics for $D(P_{true}, P_n) = O(n^{-1/d})$ are known, this approach would suggest choosing $\delta = cn^{-1/d}$.
- But this would imply solving (say for the logistic regression)

$$\min_{\beta} \{ E_{P_n} \left[\log(1 + e^{-Y\beta^T X}) \right] + cn^{-1/d} \|\beta\|_1 \}.$$

- But we know that letting $\delta = 0$ we typically obtain asymptotically normal estimators

$$\beta_n \approx \beta_{true} + n^{-1/2} N(0, \sigma^2).$$

- So, using $\delta = cn^{-1/d}$ induces an error much bigger than $n^{-1/2}$ when $d > 2$.

Towards an Optimal Choice of Uncertainty Size

- So, even if statistics for $D(P_{true}, P_n) = O(n^{-1/d})$ are known, this approach would suggest choosing $\delta = cn^{-1/d}$.
- But this would imply solving (say for the logistic regression)

$$\min_{\beta} \{ E_{P_n} \left[\log(1 + e^{-Y\beta^T X}) \right] + cn^{-1/d} \|\beta\|_1 \}.$$

- But we know that letting $\delta = 0$ we typically obtain asymptotically normal estimators

$$\beta_n \approx \beta_{true} + n^{-1/2} N(0, \sigma^2).$$

- So, using $\delta = cn^{-1/d}$ induces an error much bigger than $n^{-1/2}$ when $d > 2$.
- So, instead, we'll focus on an optimal (in some sense to be explained) approach.

Towards an Optimal Choice of Uncertainty Size

- Keep in mind linear regression problem

$$Y_i = \beta_*^T X_i + \epsilon_i.$$

Towards an Optimal Choice of Uncertainty Size

- Keep in mind linear regression problem

$$Y_i = \beta_*^T X_i + \epsilon_i.$$

- The *plausible model variations* of P_n are given by the set

$$\mathcal{U}_\delta(n) = \{P : D_c(P, P_n) \leq \delta\}.$$

Towards an Optimal Choice of Uncertainty Size

- Keep in mind linear regression problem

$$Y_i = \beta_*^T X_i + \epsilon_i.$$

- The *plausible model variations* of P_n are given by the set

$$\mathcal{U}_\delta(n) = \{P : D_c(P, P_n) \leq \delta\}.$$

- Given $P \in \mathcal{U}_\delta(n)$, define $\bar{\beta}(P) = \arg \min E_P(Y - \beta^T X)$.

Towards an Optimal Choice of Uncertainty Size

- Keep in mind linear regression problem

$$Y_i = \beta_*^T X_i + \epsilon_i.$$

- The *plausible model variations* of P_n are given by the set

$$\mathcal{U}_\delta(n) = \{P : D_c(P, P_n) \leq \delta\}.$$

- Given $P \in \mathcal{U}_\delta(n)$, define $\bar{\beta}(P) = \arg \min E_P(Y - \beta^T X)$.
- It is natural to say that

$$\Lambda_\delta(n) = \{\bar{\beta}(P) : P \in \mathcal{U}_\delta(n)\}$$

are *plausible estimates* of β_* .

Optimal Choice of Uncertainty Size

- Given a confidence level $1 - \alpha$ we advocate choosing δ via

$$\begin{aligned} & \min \delta \\ & \text{s.t. } P(\beta_* \in \Lambda_\delta(n)) \geq 1 - \alpha . \end{aligned}$$

Optimal Choice of Uncertainty Size

- Given a confidence level $1 - \alpha$ we advocate choosing δ via

$$\begin{aligned} & \min \delta \\ & \text{s.t. } P(\beta_* \in \Lambda_\delta(n)) \geq 1 - \alpha . \end{aligned}$$

- Equivalently: Find smallest confidence region $\Lambda_\delta(n)$ at level $1 - \alpha$.

Optimal Choice of Uncertainty Size

- Given a confidence level $1 - \alpha$ we advocate choosing δ via

$$\begin{aligned} & \min \delta \\ & \text{s.t. } P(\beta_* \in \Lambda_\delta(n)) \geq 1 - \alpha . \end{aligned}$$

- Equivalently: Find smallest confidence region $\Lambda_\delta(n)$ at level $1 - \alpha$.
- In simple words: Find the smallest δ so that β_* is plausible with confidence level $1 - \alpha$.

The Robust Wasserstein Profile Function

- The value $\bar{\beta}(P)$ is characterized by

$$E_P \left(\nabla_{\beta} \left(Y - \beta^T X \right)^2 \right) = 2E_P \left(\left(Y - \beta^T X \right) X \right) = 0.$$

The Robust Wasserstein Profile Function

- The value $\bar{\beta}(P)$ is characterized by

$$E_P \left(\nabla_{\beta} \left(Y - \beta^T X \right)^2 \right) = 2E_P \left(\left(Y - \beta^T X \right) X \right) = 0.$$

- Define the *Robust Wasserstein Profile (RWP) Function*:

$$R_n(\beta) = \min \{ D_c(P, P_n) : E_P \left(\left(Y - \beta^T X \right) X \right) = 0 \}.$$

The Robust Wasserstein Profile Function

- The value $\bar{\beta}(P)$ is characterized by

$$E_P \left(\nabla_{\beta} \left(Y - \beta^T X \right)^2 \right) = 2E_P \left(\left(Y - \beta^T X \right) X \right) = 0.$$

- Define the *Robust Wasserstein Profile (RWP) Function*:

$$R_n(\beta) = \min \{ D_c(P, P_n) : E_P \left(\left(Y - \beta^T X \right) X \right) = 0 \}.$$

- Note that

$$R_n(\beta_*) \leq \delta \iff \beta_* \in \Lambda_{\delta}(n) = \{ \bar{\beta}(P) : D(P, P_n) \leq \delta \}.$$

The Robust Wasserstein Profile Function

- The value $\bar{\beta}(P)$ is characterized by

$$E_P \left(\nabla_{\beta} \left(Y - \beta^T X \right)^2 \right) = 2E_P \left(\left(Y - \beta^T X \right) X \right) = 0.$$

- Define the *Robust Wasserstein Profile (RWP) Function*:

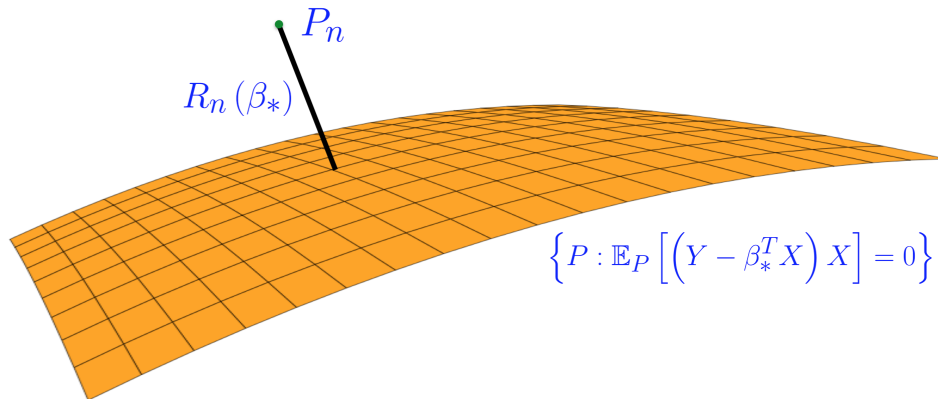
$$R_n(\beta) = \min \{ D_c(P, P_n) : E_P \left(\left(Y - \beta^T X \right) X \right) = 0 \}.$$

- Note that

$$R_n(\beta_*) \leq \delta \iff \beta_* \in \Lambda_{\delta}(n) = \{ \bar{\beta}(P) : D(P, P_n) \leq \delta \}.$$

- **So δ is $1 - \alpha$ quantile of $R_n(\beta_*)$!**

The Robust Wasserstein Profile Function



$$\left\{ P : \mathbb{E}_P \left[\left(Y - \beta_*^T X \right) X \right] = 0 \right\}$$

Computing Optimal Regularization Parameter

Theorem (B., Murthy, Kang (2016)) Suppose that $\{(Y_i, X_i)\}_{i=1}^n$ is an i.i.d. sample with finite variance, with

$$c((x, y), (x', y')) = \begin{cases} \|x - x'\|_q^2 & \text{if } y = y' \\ \infty & \text{if } y \neq y' \end{cases},$$

then

$$nR_n(\beta_*) \Rightarrow L_1,$$

where L_1 is explicitly and

$$L_1 \stackrel{D}{\leq} L_2 := \frac{E[e^2]}{E[e^2] - (E|e|)^2} \|N(0, \text{Cov}(X))\|_q^2.$$

Remark: We recover same order of regularization (but L_1 gives the optimal constant!)

Discussion on Optimal Uncertainty Size

- Optimal δ is of order $O(1/n)$ as opposed to $O(1/n^{1/d})$ as advocated in the standard approach.

Discussion on Optimal Uncertainty Size

- Optimal δ is of order $O(1/n)$ as opposed to $O(1/n^{1/d})$ as advocated in the standard approach.
- We characterize the asymptotic constant (not only order) in optimal regularization:

$$P(L_1 \leq \eta_{1-\alpha}) = 1 - \alpha.$$

Discussion on Optimal Uncertainty Size

- Optimal δ is of order $O(1/n)$ as opposed to $O(1/n^{1/d})$ as advocated in the standard approach.
- We characterize the asymptotic constant (not only order) in optimal regularization:

$$P(L_1 \leq \eta_{1-\alpha}) = 1 - \alpha.$$

- $R_n(\beta_*)$ is inspired by Empirical Likelihood – Owen (1988).

A Toy Example Illustrating Proof Techniques

- Consider

$$\min_{\beta} \max_{P: \mathcal{D}_c(P, P_n) \leq \delta} E \left[(Y - \beta)^2 \right]$$

with $c(y, y') = (y - y')^\rho$ and define

$$\begin{aligned} R_n(\beta) &= \min_{\pi(dy, du) \geq 0} \int (y - u)^\rho \pi(dy, du) : \\ &\int_{u \in \mathbb{R}} \pi(dy, du) = \frac{1}{n} \delta_{\{Y_i\}}(dy) \quad \forall i, \\ &2 \int \int (u - \beta) \pi(dy, du) = 0. \end{aligned}$$

A Toy Example Illustrating Proof Techniques

- Dual linear programming problem: Plug in $\beta = \beta_*$

$$\begin{aligned} R_n(\beta_*) &= \sup_{\lambda \in \mathbb{R}} \left\{ -\frac{1}{n} \sum_{i=1}^n \sup_{u \in \mathbb{R}} \{ \lambda(u - \beta_*) - |Y_i - u|^\rho \} \right\} \\ &= \sup_{\lambda \in \mathbb{R}} \left\{ -\frac{1}{n} \sum_{i=1}^n \sup_{u \in \mathbb{R}} \left\{ \lambda(u - Y_i) - |Y_i - u|^\rho \right\} - \frac{\lambda}{n} \sum_{i=1}^n (Y_i - \beta_*) \right\} \\ &= \sup_{\lambda} \left\{ -\frac{\lambda}{n} \sum_{i=1}^n (Y_i - \beta_*) - (\rho - 1) \left| \frac{\lambda}{\rho} \right|^{\frac{\rho}{\rho-1}} \right\} \\ &= \left| \frac{1}{n} \sum_{i=1}^n (Y_i - \beta_*) \right|^\rho = \frac{1}{n^{1/2}} |N(0, \sigma^2)|^\rho. \end{aligned}$$

Computational Tools

- Fast computation of Optimal Transport Distances is an active topic of research currently.

- Fast computation of Optimal Transport Distances is an active topic of research currently.
- Fastest algorithm for solving

$$\min_{\pi(i,j) \geq 0} \sum c(i,j) \pi(i,j)$$
$$\sum_{j=1}^n \pi(i,j) = \mu(i) \quad \forall i, \quad \sum_{i=1}^n \pi(i,j) = \nu(j) \quad \forall j$$

is in Quanrud '18 (arxiv/1810.05957B) and B., Kent, Jambulapati, Kent, Sidford '18, (arxiv/1810.07717) it runs in $O(n^2 \|c\|_\infty / \varepsilon)$ time for ε -additive error.

- Fast computation of Optimal Transport Distances is an active topic of research currently.
- Fastest algorithm for solving

$$\min_{\pi(i,j) \geq 0} \sum c(i,j) \pi(i,j)$$
$$\sum_{j=1}^n \pi(i,j) = \mu(i) \quad \forall i, \quad \sum_{i=1}^n \pi(i,j) = \nu(j) \quad \forall j$$

is in Quanrud '18 (arxiv/1810.05957B) and B., Kent, Jambulapati, Kent, Sidford '18, (arxiv/1810.07717) it runs in $O(n^2 \|c\|_\infty / \varepsilon)$ time for ε -additive error.

- Optimal complexity algorithms for continuous problems is still an open problem.

Discussion: Some Open Problems

- Extensions: Optimal Transport with constraints, Optimal Martingale Transport.

Discussion: Some Open Problems

- Extensions: Optimal Transport with constraints, Optimal Martingale Transport.
- Computational methods: Typical approach is entropic regularization (new methods currently developed in the machine learning literature).

Conclusions

- Optimal transport (OT) is a powerful tool based on linear programming.

Conclusions

- Optimal transport (OT) is a powerful tool based on linear programming.
- Arises in Economics, Machine Learning, Operations Research, Statistics, etc.

Conclusions

- Optimal transport (OT) is a powerful tool based on linear programming.
- Arises in Economics, Machine Learning, Operations Research, Statistics, etc.
- OT can be used in path-space to quantify model error.

Conclusions

- Optimal transport (OT) is a powerful tool based on linear programming.
- Arises in Economics, Machine Learning, Operations Research, Statistics, etc.
- OT can be used in path-space to quantify model error.
- OT can be used for data-driven distributionally robust optimization.

Conclusions

- Optimal transport (OT) is a powerful tool based on linear programming.
- Arises in Economics, Machine Learning, Operations Research, Statistics, etc.
- OT can be used in path-space to quantify model error.
- OT can be used for data-driven distributionally robust optimization.
- Cost function in OT can be used to improve out-of-sample performance.

Conclusions

- Optimal transport (OT) is a powerful tool based on linear programming.
- Arises in Economics, Machine Learning, Operations Research, Statistics, etc.
- OT can be used in path-space to quantify model error.
- OT can be used for data-driven distributionally robust optimization.
- Cost function in OT can be used to improve out-of-sample performance.
- OT can be used for statistical inference using RWP function.